# Extended Addressing Machines for PCF, with Explicit Substitutions 

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#### Abstract

Addressing machines have been introduced as a formalism to construct models of the pure, untyped $\lambda$-calculus. We extend the syntax of their programs by adding instructions for executing arithmetic operations on natural numbers, and introduce a reflection principle allowing certain machines to access their own address and perform recursive calls. We prove that the resulting extended addressing machines naturally model a weak call-by-name PCF with explicit substitutions. Finally, we show that they are also well-suited for representing regular PCF programs (closed terms) computing natural numbers.


Keywords: Addressing machines, PCF, explicit substitutions, computational model.

## Introduction

Turing machines (TM) and $\lambda$-calculus constitute two fundamental formalisms in theoretical computer science. Because of the difficulty in emulating higher-order calculations on a TM, their equivalence on partial numeric functions is not obtained directly, but rather composing different encodings. As a consequence, no model of $\lambda$-calculus ( $\lambda$-model) based on TM's has arisen in the literature so far. Recently, Della Penna et al. have successfully built a $\lambda$-model based on so-called addressing machines (AM) [11]. The intent is to propose a model of computation, alternative to von Neumann architecture, where computation is based on communication between machines rather than performing local operations. In fact, these machines are solely capable of manipulating the addresses of other machines - this opens the way for modelling higherorder computations since functions can be passed via their addresses. An AM can read an address from its input-tape, store in a register the result of applying an address to another and, finally, pass the execution

[^0]to another machine by calling its address (possibly extending its input-tape). The set of instructions is deliberately small, to identify the minimal setting needed to represent $\lambda$-terms. The downside is that performing calculations on natural numbers is as awkward as using Church numerals in $\lambda$-calculus.

Contents. In this paper we extend the formalism of AM's with a set of instructions representing basic arithmetic operations and conditional tests on natural numbers. As we are entering a world of machines and addresses, we need specific machines to represent numerals and assign them recognizable addresses. Finally, in order to model recursion, we rely on the existence of machines representing fixed point combinators. These machines can be programmed in the original formalism but we can avoid any dependency on self-application by manipulating the addressing mechanism so that they have access to their own address. This can be seen as a very basic version of the reflection principle which is present in some programming languages. We call the resulting formalism extended addressing machines (EAMs).

Considering these features, one might expect EAMs to be well-suited for simulating Plotkin's Programming Computable Functions (PCF) [23], a simply typed $\lambda$-calculus with constants, arithmetical operations, conditional testing and a fixed point combinator. A PCF term of the form $(\lambda x \cdot M) N$ can indeed be translated into a machine M reading as input $(x)$ from its tape the address of N . As M has control over the computation, it naturally models a weak leftmost call-by-name evaluation. However, while in the contractum $M[N / x]$ of the redex the substitution is instantaneous, M needs to pass the address of N to the machines representing the subterms of $M$, with the substitution only being performed if N gains control of the computation. As a result, rather than PCF, EAMs naturally emulate the behavior of EPCF - a weak call-by-name PCF with explicit substitutions that are only performed "on demand", as in [19]. We endow EAMs with a typing mechanism based on simple types and define a type-preserving translation from well-typed EPCF terms to EAMs. Subsequently, we prove that also the operational behavior of EPCF is faithfully represented by the translation. Finally, by showing the equivalence between PCF and EPCF on terminating programs of type int, we are capable of drawing conclusions for the original language PCF.

In this paper we mainly focus on the properties of the translation, but our long-term goal is to construct a sequential model of higher-order computations. The problem of finding a fully abstract model of PCF was originally proposed by Robin Milner in [21] and is a difficult one. A model is called fully abstract (FA) whenever two programs sharing the type $\alpha$ get the same denotation in the model if and only if they are observationally indistinguishable when plugged in the same context $C[]$ of type $\alpha \rightarrow$ int. Therefore, a FA model provides a semantic characterization of the observational equivalence of PCF. Quoting from [3]:
"the problem is to understand what should be meant by a semantic characterization [...] Our view is that the essential content of the problem, what makes it important, is that it calls for a semantic characterization of sequential, functional computation at higher-types".
A celebrated result is that FA models of PCF can be obtained by defining suitable categories of games [4,3,13]. Preliminary investigations show that EAMs open the way to construct a more 'computational' FA model. E.g., in [21], the model construction starts with first-order definable functions and requires - to cope with fixed point operator - the addition of extra 'limit points' to ensure that the resulting partial order is direct complete. In the game semantics approach the fixed point operator is treated similarly, namely via its canonical interpretation in a cpo-enriched Cartesian closed category [4]. On the contrary, in our approach no limit construction is required to give the fixed point operator a meaning. The fact that EAMs possess a given recursor having its own address stored inside is easily obtained from a mathematical point of view and, as argued above, can be seen as an abstract view of the usual implementation of recursion. We believe this new point of view may increase our understanding of PCF observational equivalence.

Outline. The paper is organized as follows. In Section 1 we introduce the language EPCF along with its syntax, simply typed assignment system and associated (call-by-name) big-step operational semantics. In Section 2 we define EAMs (no familiarity with [11] is assumed) and introduce their operational semantics. In Section 3 we describe a type-checking algorithm for determining whether an EAM is well-typed. In Section 4 we present our main results, namely:
(i) the translation of a well-typed EPCF term is an EAM typable with the same type (Theorem 4.6);
(ii) if an EPCF term reduces to a value, then their translations as machines are interconvertible (Thm. 4.7);

$$
\begin{aligned}
& \frac{\underline{n} \in \mathbb{N}}{\sigma \triangleright \underline{n} \Downarrow_{d} \underline{n}} \text { (nat) } \quad \overline{\sigma \triangleright \lambda x . M\langle\rho\rangle \Downarrow_{d} \lambda x . M\langle\sigma+\rho\rangle} \text { (fun) } \quad \frac{\sigma(x)=(\rho, N) \quad \rho \triangleright N \Downarrow_{d} V}{\sigma \triangleright x \Downarrow_{d} V} \text { (var) } \\
& \frac{\sigma \triangleright M \cdot(\operatorname{fix} M) \Downarrow_{d} V}{\sigma \triangleright \operatorname{fix} M \Downarrow_{d} V}(\text { fix }) \frac{\sigma \triangleright M \Downarrow_{d} \underline{0} \quad \sigma \triangleright N_{1} \Downarrow_{d} V_{1}}{\sigma \triangleright \operatorname{ifz}\left(M, N_{1}, N_{2}\right) \Downarrow_{d} V_{1}}(\text { ifz }) \quad \frac{\sigma \triangleright M \Downarrow_{d} \underline{n+1}}{\sigma \triangleright \mathbf{i f z}\left(M, N_{1}, N_{2}\right) \Downarrow_{d} V_{2}}\left(\text { ifz } N_{>0}\right) \\
& \frac{\sigma \triangleright M \Downarrow_{d} \underline{n+1}}{\sigma \triangleright \operatorname{pred} M \Downarrow_{d \underline{n}}}(\mathrm{pr}) \quad \frac{\sigma \triangleright M \Downarrow_{d} \underline{0}}{\sigma \triangleright \operatorname{pred} M \Downarrow_{d} \underline{0}}\left(\mathrm{pr}_{0}\right) \quad \frac{\sigma \triangleright M \Downarrow_{d} \underline{n}}{\sigma \triangleright \operatorname{succ} M \Downarrow_{d} \underline{n+1}}(\mathrm{sc}) \\
& \frac{\sigma \triangleright M \Downarrow_{d} \lambda x \cdot M^{\prime}\langle\rho\rangle \quad \rho+[x \leftarrow(\sigma, N)] \triangleright M^{\prime} \Downarrow_{d} V}{\sigma \triangleright M \cdot N \Downarrow_{d} V}\left(\beta_{v}\right)
\end{aligned}
$$

Fig. 1. The big-step operational semantics of EPCF.
(iii) the operational semantics of PCF and EPCF coincide on terminating programs of type int (Thm. 4.13);
(iv) the translation of a PCF program computing a number is an EAM evaluating the corresponding numeral (Theorem 4.14).
Related works. A preliminary version of AMs was introduced in Della Penna's MSc thesis [10] in order to model computation as communication between distinguished processes by means of their addresses. They were subsequently refined in [11] with the theoretical purpose of constructing a model of $\lambda$-calculus. Similarly, our paper should be seen as a first step towards the construction of a denotational model of PCF. Thus, the natural comparison is ${ }^{6}$ with other models rather than other machine-based formalisms that have been proposed in the literature (e.g., call-by-name: SECD [16], KAM [15], call-by-need: TIM [12], Lazy KAM $[6,17]$ ); call-by-value: ZINC [18]) from which they differ at an implementational level.

Compared with models of PCF based on Scott-continuous functions [21,5,7], EAMs provide a more operational interpretation of a program and naturally avoid parallel features that would lead to the failure of FA as in the continuous semantics. Compared with Curien's sequential algorithms [8] and categories of games $[4,13]$ they share the intensionality of programs' denotations, while presenting an original way of modelling sequential computation. The model based on AMs also bares some similarities with the categories of assembly used to model PCF [20], mostly on a philosophical level, in the sense that these models are based on the 'codes' (rather than addresses) of recursive functions realizing a formula ( $\cong$ type).

Concerning explicit substitutions we refer to the pioneering articles [1,2,9,19]. Explicit substitutions have been barely considered in the context of PCF-with the notable exception of [24].

## 1 Preliminaries

The paradigmatic programming language PCF [23] is a simply typed $\lambda$-calculus enriched with constants representing natural numbers, the fundamental arithmetical operations, an if-then-else conditional instruction, and a fixed-point operator. We give PCF for granted and rather present EPCF, an extension of PCF with explicit substitutions [19]. We draw conclusions for the standard PCF by exploiting the fact that they are equivalent on programs (closed terms) of type int.
Definition 1.1 Consider fixed a countably infinite set Var of variables. EPCF terms and explicit substitutions are defined by (for $n \geq 0$ and $\vec{x} \in \operatorname{Var}$ ):

$$
\begin{aligned}
& L, M, N::=x|M \cdot N| \lambda x \cdot M\langle\sigma\rangle|\mathbf{0}| \operatorname{pred} M|\operatorname{succ} M| \operatorname{ifz}(L, M, N) \mid \operatorname{fix} M \\
& \sigma, \rho \quad::=\left[x_{1} \leftarrow\left(\sigma_{1}, M_{1}\right), \ldots, x_{n} \leftarrow\left(\sigma_{n}, M_{n}\right)\right]
\end{aligned}
$$

As is customary, $M \cdot N$ stands for the application of a term $M$ to its argument $N, \mathbf{0}$ represents the

[^1]natural number 0, pred and succ indicate the predecessor and successor respectively, ifz is the conditional test on zero, and finally, fix is a fixed-point operator. We assume that application - often denoted as juxtaposition - associates to the left and has higher precedence than abstraction. Concerning $\lambda x . M\langle\sigma\rangle$, it represents an abstraction where $\sigma$ is a list of assignments from variables to closures (terms with the associated substitutions), where each variable can only have one closure assigned to it.
Definition 1.2 (i) In an explicit substitution
$$
\sigma=\left[x_{1} \leftarrow\left(\sigma_{1}, M_{1}\right), \ldots, x_{n} \leftarrow\left(\sigma_{n}, M_{n}\right)\right]
$$
the $x_{i}$ 's are assumed to be fresh and distinguished.
(ii) By (i), we can define $\sigma\left(x_{i}\right)=\left(\sigma_{i}, M_{i}\right)$.
(iii) The domain of $\sigma$ is given by $\operatorname{dom}(\sigma)=\left\{x_{1}, \ldots, x_{n}\right\}$.
(iv) We write $\sigma+\rho$ for the concatenation of $\sigma$ and $\rho$, and in this case we assume $\operatorname{dom}(\sigma) \cap \operatorname{dom}(\rho)=\emptyset$.

The set $\mathrm{FV}(M)$ of free variables of an EPCF term $M$ is defined as usual, except for the abstraction case $\mathrm{FV}(\lambda x \cdot M\langle\sigma\rangle)=\mathrm{FV}(M)-(\{x\} \cup \operatorname{dom}(\sigma))$. The term $M$ is closed if $\mathrm{FV}(M)=\emptyset$, and in that case it is called an EPCF program.

Hereafter terms are considered up to renaming of bound variables. Therefore the symbol = will denote syntactic equality up to $\alpha$-conversion.
Notation 1 (i) For every $n \in \mathbb{N}$, we let $\underline{n}=\operatorname{succ}^{n}(\mathbf{0})$. In particular, $\underline{0}$ is an alternative notation for $\mathbf{0}$.
(ii) As a syntactic sugar, we write $\lambda x . M$ for $\lambda x \cdot M\rangle$. With this notation in place, PCF terms are simply EPCF terms containing empty explicit substitutions.
(iii) For $n \in \mathbb{N}$, we often write $\lambda x_{1} \ldots \lambda x_{n} . M$ as $\lambda x_{1} \ldots x_{n}$. $M$, or even $\lambda \vec{x} . M$ when $n$ is clear from the context. Summing up, and recalling that $\cdot$ is left associative, $\lambda x_{1} x_{2} x_{3} . L \cdot M \cdot N$ stands for $\lambda x_{1} \cdot\left(\lambda x_{2} \cdot\left(\lambda x_{3} \cdot((L \cdot M) \cdot N)\langle \rangle\right)\langle \rangle\right)\langle \rangle$.
(iv) $M[N / x]$ denotes the capture-free substitution of $N$ for all free occurrences of $x$ in $M$.

Example 1.3 We introduce some notations for the following (E)PCF programs, that will be used as running examples.
(i) $\mathbf{I}=\lambda x \cdot x$, representing the identity.
(ii) $\boldsymbol{\Omega}=\mathrm{fix}(\mathbf{I})$ representing the paradigmatic looping program.
(iii) $\operatorname{succ} 1=\lambda x \cdot \boldsymbol{\operatorname { s u c c }}(x)$, representing the successor function.
(iv) $\operatorname{succ} 2=(\lambda$ sn.s $\cdot(s \cdot n)) \cdot$ succ1, representing the function $f(x)=x+2$.
(v) add_aux $=\lambda f x y \cdot \operatorname{ifz}(y, x,(f \cdot(\operatorname{succ} x)) \cdot(\operatorname{pred} y))$, i.e. the functional

$$
\Phi_{f}(x, y)= \begin{cases}x, & \text { if } y=0 \\ f(x+1, y-1), & \text { if } y>0\end{cases}
$$

$(\mathrm{vi})$ add $=\mathrm{fix}($ add_aux $)$, i.e., the recursive definition of addition $f(x, y)=x+y$.
The operational semantics of EPCF is defined via a call-by-name big-step (leftmost) weak reduction.
Definition 1.4 (i) We let Val $=\{\underline{n} \mid n \in \mathbb{N}\} \cup\{\lambda x \cdot M\langle\sigma\rangle \mid M$ is an EPCF term $\}$ be the set of EPCF values.
(ii) The big-step weak reduction is the least relation $\Downarrow_{d}$ from EPCF terms to Val, closed under the rules of Figure 1.
(iii) We say that an EPCF program $M$ is terminating whenever $M \Downarrow_{d} V$ holds, for some $V \in$ Val. Otherwise, we say that $M$ is a non-terminating, or looping, term.

Example 1.5 We show some of the terms from Example 1.3, at work.

$$
\overline{\Gamma, x: \alpha \vdash^{\mathrm{E}} x: \alpha}(\mathrm{ax}) \quad \overline{\Gamma \vdash^{\mathrm{E}} \mathbf{0}: \text { int }}(0) \quad \frac{\Gamma \vdash^{\mathrm{E}} M: \alpha \rightarrow \alpha}{\Gamma \vdash^{\mathrm{E}} \text { fix } M: \alpha}(\mathrm{Y})
$$

$$
\frac{\Gamma \vdash^{\mathrm{E}} M: \mathrm{int}}{\Gamma \vdash^{\mathrm{E}} \operatorname{succ} M: \text { int }}(+) \quad \frac{\Gamma \vdash^{\mathrm{E}} M: \mathrm{int}}{\Gamma \vdash^{\mathrm{E}} \text { pred } M: \mathrm{int}}(-) \quad \frac{\sigma \models \Delta \quad \Gamma, \Delta, x: \alpha \vdash^{\mathrm{E}} M: \beta}{\Gamma \vdash^{\mathrm{E}} \lambda x \cdot M\langle\sigma\rangle: \alpha \rightarrow \beta}\left(\rightarrow_{\mathrm{I}}\right)
$$

$$
\begin{equation*}
\frac{\Gamma \vdash^{\mathrm{E}} M: \alpha \rightarrow \beta \quad \Gamma \vdash^{\mathrm{E}} N: \alpha}{\Gamma \vdash^{\mathrm{E}} M \cdot N: \beta}\left(\rightarrow_{\mathrm{E}}\right) \tag{ifz}
\end{equation*}
$$

$$
\frac{\Gamma \vdash^{\mathrm{E}} L: \operatorname{int} \quad \Gamma \vdash^{\mathrm{E}} M: \alpha \quad \Gamma \vdash^{\mathrm{E}} N: \alpha}{\Gamma \vdash^{\mathrm{E}} \mathrm{ifz}(L, M, N): \alpha}
$$

$$
\overline{[] \models \emptyset}\left(\sigma_{0}\right)
$$

Fig. 2. EPCF type assignment system.
(i) We have [] $\triangleright \operatorname{succ} \mathbf{1} \cdot \mathbf{0} \Downarrow_{d} \underline{1}$. To get the reader familiar with the operational semantics, we give the details:

$$
\frac{\frac{\overline{[] \triangleright \underline{0} \Downarrow_{d} \underline{0}}(\text { nat })}{[] \triangleright \lambda x \cdot \operatorname{succ}(x) \Downarrow_{d} \lambda x \cdot \operatorname{succ}(x)}(\text { fun }) \frac{\frac{\leftarrow([], \underline{0})] \triangleright x \Downarrow_{d} \underline{0}}{[x \leftarrow}(\text { var })}{[x \leftarrow([], \underline{0})] \triangleright \operatorname{succ}(x) \Downarrow_{d} \underline{1}}}{[\mathrm{sc})}\left(\beta_{v}\right)
$$

(ii) Similarly, []$\triangleright \mathbf{I} \cdot \underline{4} \Downarrow_{d} \underline{4}, \quad[] \triangleright \mathbf{I} \cdot \mathbf{I} \Downarrow_{d} \mathbf{I}, \quad[] \triangleright \operatorname{succ} \mathbf{2} \cdot \underline{1} \Downarrow_{d} \underline{3}$ and []$\triangleright \operatorname{add} \cdot \underline{5} \cdot \underline{1} \Downarrow_{d} \underline{6}$.
(iii) Since $\boldsymbol{\Omega}$ is looping, there is no $V \in \operatorname{Val}$ such that []$\triangleright \boldsymbol{\Omega} \Downarrow_{d} V$ is derivable.

We now endow EPCF terms with a type system based on simple types.
Definition 1.6 (i) The set $\mathbb{T}$ of (simple) types over a ground type int is inductively defined by the grammar:

$$
\begin{equation*}
\alpha, \beta::=\operatorname{int} \mid \alpha \rightarrow \beta \tag{T}
\end{equation*}
$$

The arrow associates to the right, in other words we write $\alpha_{1} \rightarrow \cdots \rightarrow \alpha_{n} \rightarrow \beta$ for $\alpha_{1} \rightarrow\left(\cdots \rightarrow\left(\alpha_{n} \rightarrow \beta\right) \cdots\right)(=\vec{\alpha} \rightarrow \beta$, for short $)$.
(ii) A typing context $\Gamma$ is given by a set of associations between variables and types, written $x_{1}$ : $\alpha_{1}, \ldots, x_{n}: \alpha_{n}$. In this case, we let $\operatorname{dom}(\Gamma)=\left\{x_{1}, \ldots, x_{n}\right\}$. When writing $\Gamma, x: \alpha$, we silently assume that $x \notin \operatorname{dom}(\Gamma)$.
(iii) Typing judgements are triples, denoted $\Gamma \vdash^{\mathrm{E}} M: \alpha$, where $\Gamma$ is a typing context, $M$ is an EPCF term and $\alpha \in \mathbb{T}$.
(iv) Typing derivations are finite trees built bottom-up in such a way that the root has shape $\Gamma \vdash^{\mathrm{E}} M: \alpha$ and every node is an instance of a rule from Figure 2. In the rule $\left(\rightarrow_{\mathrm{I}}\right)$ we assume wlog that $x \notin \Gamma$, by $\alpha$-conversion. We also use an auxiliary predicate $\sigma \models \Gamma$ whose intuitive meaning is that $\Gamma$ is a typing context constructed from an explicit substitution $\sigma$.
(v) When writing $\Gamma \vdash^{\mathrm{E}} M: \alpha$, we mean that this typing judgement is derivable.
(vi) We say that $M$ is typable if $\Gamma \vdash^{\mathrm{E}} M: \alpha$ is derivable for some $\Gamma, \alpha$.

Example 1.7 The following are examples of derivable typing judgments.
(i)
(ii) $\vdash^{\mathrm{E}}(\lambda x \cdot \operatorname{succ}(x)) \cdot \mathbf{0}:$ int.
(iii) $\vdash^{\mathrm{E}}(\lambda s n . s \cdot(s \cdot n)) \cdot(\lambda x$.succ $(x)):$ int $\rightarrow$ int.
(iv) $\vdash^{\mathrm{E}} \mathbf{f i x}(\lambda f x y . \operatorname{ifz}(y, x, f \cdot(\boldsymbol{\operatorname { s u c c }} x) \cdot(\operatorname{pred} y))):$ int $\rightarrow$ int $\rightarrow$ int.
(v) $\vdash^{\mathrm{E}} \Omega: \alpha$, for all $\alpha \in \mathbb{T}$.

The following lemma summarizes the main (rather standard) properties of the language EPCF.
Lemma 1.8 Let $M$ be an EPCF term, $V \in \operatorname{Val}, \alpha, \beta \in \mathbb{T}$ and $\Gamma$ be a context.
(i) (Syntax directedness) Every derivable judgement $\Gamma \vdash^{\mathrm{E}} M$ : $\alpha$ admits a unique derivation.
(ii) (Strengthening) If $\Gamma, x: \beta \vdash^{\mathrm{E}} M: \alpha$ and $x \notin \mathrm{FV}(M)$ then $\Gamma \vdash^{\mathrm{E}} M: \alpha$.
(iii) (Subject reduction) For $M$ closed, $\vdash^{\mathrm{E}} M: \alpha$ and []$\triangleright M \Downarrow_{d} V$ entail $\vdash^{\mathrm{E}} V: \alpha$.

It follows that, if an EPCF program $M$ is typable, then it is also typable in the empty context.

## 2 Extended Addressing Machines

We extend the addressing machines from [11] with instructions for performing arithmetic operations and conditional testing. Natural numbers are represented by particular machines playing the role of numerals.

### 2.1 Main definitions

We consider fixed a countably infinite set $\mathbb{A}$ of addresses together with a distinguished countable subset $\mathbb{X} \subset \mathbb{A}$, such that $\mathbb{A}-\mathbb{X}$ remains infinite. Intuitively, $\mathbb{X}$ is the set of addresses that we reserve for the numerals, therefore hereafter we work under the hypothesis that $\mathbb{X}=\mathbb{N}$, an assumption that we can make without loss of generality.

Let $\varnothing \notin \mathbb{A}$ be a "null" constant corresponding to an uninitialised register. Set $\mathbb{A}_{\varnothing}=\mathbb{A} \cup\{\varnothing\}$.
Definition 2.1 (i) An $\mathbb{A}$-valued tape $T$ is a finite ordered list of addresses $T=\left[a_{1}, \ldots, a_{n}\right]$ with $a_{i} \in \mathbb{A}$ for all $i(1 \leq i \leq n)$. When $\mathbb{A}$ is clear from the context, we simply call $T$ a tape. We denote by $\mathcal{T}_{\mathbb{A}}$ the set of all $\mathbb{A}$-valued tapes.
(ii) Let $a \in \mathbb{A}$ and $T, T^{\prime} \in \mathcal{T}_{\mathbb{A}}$. We denote by $a:: T$ the tape having $a$ as first element and $T$ as tail. We write $T @ T^{\prime}$ for the concatenation of $T$ and $T^{\prime}$, which is an $\mathbb{A}$-valued tape itself.
(iii) Given an index $i \geq 0$, an $\mathbb{A}_{\varnothing}$-valued register $R_{i}$ is a memory-cell capable of storing either $\varnothing$ or an address $a \in \mathbb{A}$. We write $!R_{i}$ to represent the value stored in the register $R_{i}$. (The notation $!R_{i}$ is borrowed from ML, where ! represents an explicit dereferencing operator.)
(iv) Given $\mathbb{A}_{\varnothing}$-valued registers $R_{0}, \ldots, R_{n}$ for $n \geq 0$, an address $a \in \mathbb{A}$ and an index $i \geq 0$, we write $\vec{R}\left[R_{i}:=a\right]$ for the list of registers $\vec{R}$ where the value of $R_{i}$ has been updated by setting $!R_{i}=a$. Notice that, whenever $i>n$, we assume that the contents of $\vec{R}$ remains unchanged, i.e. $\vec{R}\left[R_{i}:=a\right]=\vec{R}$.

Intuitively, the contents of the registers $R_{0}, \ldots, R_{n}$ constitutes the state of a machine, while the tape correspond to the list of its inputs. The addressing machines from [11] are endowed with only three instructions ( $i, j, k, l$ range over indices of registers):

1. Load $i$ : reads an address $a$ from the input tape, assuming it is non-empty, and stores $a$ in the register $R_{i}$. If the tape is empty then the machine suspends its execution without raising an error.
2. $k \leftarrow \operatorname{App}(i, j)$ : reads the addresses $a_{1}, a_{2}$ from $R_{i}$ and $R_{j}$ respectively, and stores in $R_{k}$ the address of the machine obtained by extending the tape of the machine of address $a_{1}$ with the address $a_{2}$. The resulting address is not calculated internally but rather obtained calling an external application map.
3. Call $i$ : transfers the computation to the machine having as address the value stored in $R_{i}$, whose tape is extended with the remainder of the current machine's tape.
As a general principle, writing on a non-existing register does not cause issues as the value is simply discarded - this is in fact the way one can erase an argument. The attempt of reading an uninitialized
register would raise an error-we however show that these kind of errors can be avoided statically (see Lemma 2.4).

We enrich the above set of instructions with arithmetic operations mimicking the ones present in PCF:
4. $l \leftarrow \operatorname{Test}(i, j, k)$ : implements the "is zero?" test on ! $R_{i}$. Assuming that the value of $R_{i}$ is an address $n \in \mathbb{N}$, the instruction stores in $R_{l}$ the value of $R_{j}$ or $R_{k}$, depending on whether $n=0$.
5. $j \leftarrow \operatorname{Pred}(i):$ if $!R_{i} \in \mathbb{N}$, the value of $R_{j}$ becomes $!R_{i} \ominus 1=\max \left(!R_{i}-1,0\right)$.
6. $j \leftarrow \operatorname{Succ}(i):$ if $!R_{i} \in \mathbb{N}$, then the value of $R_{j}$ becomes $!R_{i}+1$.

Notice that the instructions above need $R_{i}$ to contain a natural number to perform the corresponding operation. However, they are also supposed to work on addresses of machines that compute a numeral. For this reason, the machine whose address is stored in $R_{i}$ must first be executed, and only if the computation terminates with a numeral is the arithmetic operation performed. Clearly, if the computation terminates in an address not representing a numeral, then an error should be raised at execution time. We will see that these kind of errors can be avoided using a type inference algorithm (see Proposition 3.5, below).
Definition 2.2 (i) A program $P$ is a finite list of instructions generated by the following grammar, where $\varepsilon$ represents the empty string and $i, j, k, l$ are indices of registers:

$$
\begin{aligned}
& \mathrm{P}::=\operatorname{Load} i ; \mathrm{P} \mid \mathrm{A} \\
& \mathrm{~A}::=k \leftarrow \operatorname{App}(i, j) ; \mathrm{A}|l \leftarrow \operatorname{Test}(i, j, k) ; \mathrm{A}| j \leftarrow \operatorname{Pred}(i) ; \mathrm{A}|j \leftarrow \operatorname{Succ}(i) ; \mathrm{A}| \mathrm{C} \\
& \mathrm{C}::=\operatorname{Call} i \mid \varepsilon
\end{aligned}
$$

Thus, a program starts with a list of Load's, continues with a list of App, Test, Pred, Succ, and possibly ends with a Call. Each of these lists may be empty, in particular the empty program $\varepsilon$ can be generated.
(ii) In a program, we write Load $\left(i_{1}, \ldots, i_{n}\right)$ as an abbreviation for the instructions Load $i_{1} ; \cdots ;$ Load $i_{n}$.
(iii) Let $P$ be a program, $r \geq 0$, and $\mathcal{I} \subseteq\{0, \ldots, r-1\}$ be a set of indices corresponding to the indices of initialized registers. Define the relation $\mathcal{I} \models^{r} P$, whose intent is to specify that $P$ does not read uninitialized registers, as the least relation closed under the rules:

$$
\begin{aligned}
& \overline{\mathcal{I} \models^{r} \varepsilon} \quad \frac{i \in \mathcal{I}}{\mathcal{I} \models^{r} \operatorname{Call} i} \frac{\mathcal{I} \cup\{j\} \models^{r} \mathrm{~A} \quad i \in \mathcal{I} \quad j<r}{\mathcal{I} \models^{r} j \leftarrow \operatorname{Pred}(i) ; \mathrm{A}} \\
& \frac{\mathcal{I} \cup\{i\} \not \models^{r} \mathrm{P} \quad i<r}{\mathcal{I} \models^{r} \text { Load } i ; \mathrm{P}} \quad \frac{\mathcal{I} \models^{r} \mathrm{P} \quad i \geq r}{\mathcal{I} \models^{r} \text { Load } i ; \mathrm{P}} \frac{\mathcal{I} \cup\{j\} \models^{r} \mathrm{~A} \quad i \in \mathcal{I} \quad j<r}{\mathcal{I} \models^{r} j \leftarrow \operatorname{Succ}(i) ; \mathrm{A}} \\
& \frac{\mathcal{I} \cup\{k\} \models^{r} \mathrm{~A} \quad i, j \in \mathcal{I} \quad k<r}{\mathcal{I} \models^{r} k \leftarrow \operatorname{App}(i, j) ; \mathrm{A}} \quad \frac{\mathcal{I} \cup\{l\} \models^{r} \mathrm{~A} \quad i, j, k \in \mathcal{I} \quad l<r}{\mathcal{I} \models^{r} l \leftarrow \operatorname{Test}(i, j, k) ; \mathrm{A}}
\end{aligned}
$$

(iv) A program $P$ is valid with respect to $R_{0}, \ldots, R_{r-1}$ if $\mathcal{R} \models^{r} P$ holds for $\mathcal{R}=\left\{i \mid R_{i} \neq \varnothing \wedge 0 \leq i<r\right\}$.

Example 2.3 For each of these programs, we specify its validity with respect to $R_{0}=7, R_{1}=a, R_{2}=\varnothing$ (i.e., $r=3$ ).

$$
\begin{align*}
& P_{1}=2 \leftarrow \operatorname{Pred}(0) ; \text { Call } 2  \tag{valid}\\
& P_{2}=\operatorname{Load}(2,8) ; 0 \leftarrow \operatorname{Test}(0,1,2) ; \text { Call } 0  \tag{valid}\\
& P_{3}=\operatorname{Load}(0,2,8) ; \text { Call } 8
\end{align*}
$$

(calling the uninitialized register $R_{8}$, thus not valid)
Lemma 2.4 Given $\mathbb{A}_{\varnothing}$-valued registers $\vec{R}$ and a program $P$ it is decidable whether $P$ is valid w.r.t. $\vec{R}$.

Proof. Decidability follows from the syntax directedness of Definition 2.2 (iii), and the preservation of the invariant $\mathcal{I} \subseteq\{0, \ldots, r-1\}$, since $\mathcal{I}$ is only extended with $k<r$.
Definition 2.5 (i) An extended addressing machine ( $E A M$ ) M with $r$ registers over $\mathbb{A}$ is given by a tuple:

$$
\mathrm{M}=\left\langle R_{0}, \ldots, R_{r-1}, P, T\right\rangle
$$

where $\vec{R}$ are $\mathbb{A}_{\varnothing}$-valued registers, $P$ is a program valid w.r.t. $\vec{R}$ and $T \in \mathcal{T}_{\mathbb{A}}$ is an (input) tape.
(ii) We write M.r for the number of registers of M, M. $R_{i}$ for its $i$-th register, M. $P$ for the associated program and M.T for its input tape. When writing " $R_{i}=a$ " in a tuple we indicate that $R_{i}$ is present and $!R_{i}=a$.
(iii) We say that an extended addressing machine M as above is stuck, written stuck( M ), whenever its program has shape M. $P=$ Load $i ; P$ but its input-tape is empty M.T $=[]$. Otherwise M is ready, written $\neg$ stuck(M).
(iv) The set of all extended addressing machines over $\mathbb{A}$ will be denoted by $\mathcal{M}_{\mathbb{A}}$.
(v) For $n \geq 0$, the $n$-th numeral machine is defined $\mathrm{n}=\left\langle R_{0}, \varepsilon,[]\right\rangle$ with $!R_{0}=n$.
(vi) For $n \geq 0$ and $a \in \mathbb{A}$, define

$$
Y_{n}^{a}=\left\langle\left(R_{0}=a, R_{1}=\varnothing, \ldots, R_{n+1}=\varnothing, P,[]\right\rangle\right.
$$

where $P=\operatorname{Load}(1, \ldots, n+1) ; 0 \leftarrow \operatorname{App}(0,1) ; \cdots ; 0 \leftarrow \operatorname{App}(0, n+1) ; 1 \leftarrow \operatorname{App}(1,2) ; \cdots$;

$$
1 \leftarrow \operatorname{App}(1, n+1) ; 1 \leftarrow \operatorname{App}(1,0) ; \text { Call } 1
$$

We now enter into the details of the addressing mechanism which constitutes the core of this formalism.
Definition 2.6 Recall that $\mathbb{N}$ stands for an infinite subset of $\mathbb{A}$, here identified with the set of natural numbers, and $\mathrm{Y}_{n}^{a}$ has been introduced in Definition 2.5(vi).
(i) Since $\mathcal{M}_{\mathbb{A}}$ is countable, we can fix a bijective function $\#: \mathcal{M}_{\mathbb{A}} \rightarrow \mathbb{A}$ satisfying the following conditions:
(a) (Numerals) $\forall n \in \mathbb{N} . \# \mathrm{n}=n$, where n is the $n$-th numeral machine;
(b) (Fixed point combinator) for all $n \geq 0$, there exists an address $a \in \mathbb{A}-\mathbb{N}$ such that $\#\left(\mathrm{Y}_{n}^{a}\right)=a$.

We say that the bijection $\#(\cdot)$ is an address table map and call the element $\# \mathrm{M}$ the address of the $E A M \mathrm{M}$. We simply write $\mathrm{Y}_{n}$ for the machine satisfying the equation above and $a_{\mathrm{Y}_{n}}$ for its address, i.e. $\#\left(\mathrm{Y}_{n}\right)=a_{\mathrm{Y}_{n}}$.
(ii) For $a \in \mathbb{A}$, we write $\#^{-1}(a)$ for the unique machine having address $a$, i.e., $\#^{-1}(a)=\mathrm{M} \Longleftrightarrow \# \mathrm{M}=a$.
(iii) Given $\mathrm{M} \in \mathcal{M}_{\mathbb{A}}$ and $T^{\prime} \in \mathcal{T}_{\mathbb{A}}$, we write $\mathrm{M} @ T^{\prime}$ for the machine $\left\langle\mathrm{M} . \vec{R}, \mathrm{M} . P, \mathrm{M} . T @ T^{\prime}\right\rangle$.
(iv) Define the application map $(\cdot): \mathbb{A} \times \mathbb{A} \rightarrow \mathbb{A}$ by setting $a \cdot b=\#\left(\#^{-1}(a) @[b]\right)$, i.e., the application of $a$ to $b$ is the unique address $c$ of the EAM obtained by adding $b$ at the end of the input tape of the EAM $\#^{-1}(a)$.
Example 2.7 The following are examples of EAMs (whose registers are assumed uninitialized, i.e. $\vec{R}=\vec{\varnothing}$ ).
(i) Succ1 $:=\left\langle R_{0}\right.$, Load $0 ; 0 \leftarrow \operatorname{Succ}(0)$; Call $\left.0,[]\right\rangle$.
(ii) Succ $2:=\left\langle R_{0}, R_{1}\right.$, Load 0 ; Load $1 ; 1 \leftarrow \operatorname{App}(0,1) ; 1 \leftarrow \operatorname{App}(0,1)$; Call $\left.1,\left[a_{\mathrm{S}}\right]\right\rangle$, where $a_{\mathrm{S}}=\#$ Succ1.
(iii) Add_aux $:=\langle\vec{R}, P,[]\rangle$ with Add_aux. $r=5$ and $P=\operatorname{Load}(0,1,2) ; 3 \leftarrow \operatorname{Pred}(1) ; 4 \leftarrow \operatorname{Succ}(2) ; 0 \leftarrow$ $\operatorname{App}(0,3) ; 0 \leftarrow \operatorname{App}(0,4) ; 0 \leftarrow \operatorname{Test}(1,2,0) ;$ Call 0.

Remark 2.8 In general, there are uncountably many possible address table maps of arbitrary computational complexity. A natural example of such maps is given by Gödelization, which can be performed effectively. The framework is however more general and allows to consider non-r.e. sets of addresses like the complement $K^{c}$ of the halting set

$$
K=\{(i, x) \mid \text { the program } i \text { terminates when run on input } x\}
$$

and a non-computable function $\#: \mathcal{M}_{K^{c}} \rightarrow K^{c}$ as a map.
In an implementation of EAMs the address table map should be computable one can choose a fresh address from $\mathbb{A}$ whenever a new machine is constructed, save the correspondence in some table and retrieve it in constant time.

Remark 2.9 Depending on the chosen address table map, it might be possible to construct infinite (static) chains of EAMs $(\mathrm{M})_{n \in \mathbb{N}}$, e.g., $\mathrm{M}_{n}=\left\langle R_{0}=\# \mathrm{M}_{n+1}, \varepsilon,[]\right\rangle$.

The results we present are independent from the choice of $\#$.

### 2.2 Operational semantics

The operational semantics of extended addressing machines is given through a small-step rewriting system. The reduction strategy is deterministic, since the only applicable rule at every step is univocally determined by the first instruction of the internal program, the contents of the registers and the head of the tape.

Definition 2.10 We introduce a fresh constant err $\notin \mathcal{M}_{\mathbb{A}}$ to represent a machine raising an error.
(i) Define a reduction strategy $\rightarrow_{c}$ on EAMs, representing one step of computation, as the least relation $\rightarrow_{c} \subseteq \mathcal{M}_{\mathbb{A}} \times\left(\mathcal{M}_{\mathbb{A}} \cup\{\operatorname{err}\}\right)$ closed under the rules in Figure 3.
(ii) The multistep reduction $\rightarrow_{c}$ is defined as the transitive-reflexive closure of $\rightarrow_{c}$.
(iii) Given $\mathrm{M}, \mathrm{N}, \mathrm{M} \rightarrow{ }_{c} \mathrm{~N}$, we write $\left|\mathrm{M} \rightarrow{ }_{c} \mathrm{~N}\right| \in \mathbb{N}$ for the length of the (unique) reduction path from M to N .
(iv) For $M, N \in \mathcal{M}_{\mathbb{A}}$, we write $M \leftrightarrow_{c} N$ if they have a common reduct $Z \in \mathcal{M}_{\mathbb{A}} \cup\{$ err $\}$, i.e. $M \rightarrow_{c} Z{ }_{c} \nVdash N$.
(v) An extended address machine M : is in final state if it cannot reduce, written $\mathrm{M} \not \not_{c}$; reaches a final state if $\mathrm{M} \rightarrow{ }_{c} \mathrm{M}^{\prime}$ for some $\mathrm{M}^{\prime} \in \mathcal{M}_{\mathbb{A}}$ in final state; raises an error if $\mathrm{M} \rightarrow_{c}$ err; does not terminate, otherwise.

Notice that since the redexes in Figure 3 are not overlapping, the confluence of $\rightarrow{ }_{c}$ follows easily (cf. [11, Lemma 2.11(2)]).

Lemma 2.11 If $\mathrm{M} \rightarrow{ }_{c} \mathrm{M}^{\prime}$, then $\mathrm{M} @ \# \mathrm{~N} \rightarrow{ }_{\mathrm{c}} \mathrm{M}^{\prime} @ \# \mathrm{~N}$.
Proof. By induction on the length of $\mathrm{M} \rightarrow{ }_{c} \mathrm{M}^{\prime}$.
Example 2.12 See Example 2.7 for the definition of Succ1, Succ2, Add_aux.
(i) We have Succ1 @ [0] $\rightarrow_{c} 1$ and Succ2 @ [1] $\rightarrow_{c} 3$.
(ii) Define Add $=\mathrm{Y}_{0} @[\#$ Add_aux], an EAM performing the addition. We show:

$$
\begin{aligned}
& \text { Add @ }[1,3] \rightarrow_{c}\left\langle\left(R_{0}=a_{\mathrm{Y}_{0}}, R_{1}=\text { \#Add_aux }\right), 0 \leftarrow \operatorname{App}(0,1) ; 1 \leftarrow \operatorname{App}(1,0) ; \text { Call 1, }[1,3]\right\rangle
\end{aligned}
$$

$$
\begin{aligned}
& \rightarrow{ }_{c}\left\langle\begin{array}{r}
R_{0}=\# \text { Add, } R_{1}=1, R_{2}=3, R_{3}, R_{4}, 3 \leftarrow \operatorname{Pred}(1) ; 4 \leftarrow \operatorname{Succ}(2) ; 0 \leftarrow \operatorname{App}(0,3) ; \\
0 \leftarrow \operatorname{App}(0,4) ; 0 \leftarrow \operatorname{Test}(1,2,0) ; \operatorname{Call} 0,[]
\end{array}\right\rangle \\
& \rightarrow{ }_{c}\left\langle R_{0}=\#(\text { Add } @[0,4]), R_{1}=1, R_{2}=3, R_{3}=0, R_{4}=4,0 \leftarrow \operatorname{Test}(1,2,0) ; \text { Call } 0,[]\right\rangle \\
& \rightarrow{ }_{c}\left\langle R_{0}=\#(\operatorname{Add} @[0,5]), R_{1}=0, R_{2}=4, R_{3}=0, R_{4}=5,0 \leftarrow \operatorname{Test}(1,2,0) ; \text { Call } 0,[]\right\rangle \rightarrow{ }_{c} 4
\end{aligned}
$$

(iii) For $\mathrm{I}=\left\langle R_{0}=\varnothing\right.$, Load 0; Call 0, []$\rangle, \mathrm{Y}_{0} @[\# \mathrm{I}] \rightarrow \mathrm{c} \mid$ @ $\left[\#\left(\mathrm{Y}_{0} @[\# \mathrm{I}]\right)\right]$.
(iv) $\mathrm{Y}_{n} @\left[\# \mathrm{M}, d_{1}, \ldots, d_{n}\right] \rightarrow_{c} \mathrm{M} @\left[d_{1}, \ldots, d_{n}, \#\left(\mathrm{Y}_{n} @\left[\# \mathrm{M}, d_{1}, \ldots, d_{n}\right]\right)\right]$, for all $n \geq 0, \mathrm{M} \in \mathcal{M}_{\mathbb{A}}, \vec{d} \in \mathbb{A}$.

## Unconditional rewriting rules

$$
\begin{aligned}
\langle\vec{R}, \text { Call } i ; P, T\rangle & \rightarrow_{\mathrm{c}} \#^{-1}\left(!R_{i}\right) @ T \\
\langle\vec{R}, \operatorname{Load} i ; P, a:: T\rangle & \rightarrow_{\mathrm{c}}\left\langle\vec{R}\left[R_{i}:=a\right], P, T\right\rangle \\
\langle\vec{R}, k \leftarrow \operatorname{App}(i, j) ; P, T\rangle & \rightarrow_{\mathrm{c}}\left\langle\vec{R}\left[R_{k}:=!R_{i} \cdot!R_{j}\right], P, T\right\rangle
\end{aligned}
$$

Under the assumption that $\#^{-1}\left(!R_{i}\right) \not \not_{c}$ (i.e., it is in final state).

$$
\begin{array}{r}
\langle\vec{R}, j \leftarrow \operatorname{Pred}(i) ; P, T\rangle \rightarrow_{c} \begin{cases}\left\langle\vec{R}\left[R_{j}:=!R_{i} \ominus 1, P, T\right\rangle,\right. & \text { if }!R_{i} \in \mathbb{N}, \\
\text { err, } & \text { otherwise. }\end{cases} \\
\langle\vec{R}, j \leftarrow \operatorname{Succ}(i) ; P, T\rangle \rightarrow_{c} \begin{cases}\left\langle\vec{R}\left[R_{j}:=!R_{i} \oplus 1, P, T\right\rangle,\right. & \text { if }!R_{i} \in \mathbb{N}, \\
\text { err, } & \text { otherwise } .\end{cases} \\
\langle\vec{R}, l \leftarrow \operatorname{Test}(i, j, k) ; P, T\rangle \rightarrow_{c} \begin{cases}\left\langle\vec{R}\left[R_{l}:=!R_{j}\right], P, T\right\rangle, & \text { if }!R_{i}=0, \\
\left\langle\vec{R}\left[R_{l}:=!R_{k}\right], P, T\right\rangle, & \text { if }!R_{i} \in \mathbb{N}^{+}, \\
\text {err }, & \text { otherwise. }\end{cases}
\end{array}
$$

Under the assumption that $\#^{-1}\left(!R_{i}\right) \rightarrow_{\mathrm{c}} \mathrm{A}$ (i.e., it is not in final state).

$$
\begin{aligned}
\langle\vec{R}, j \leftarrow \operatorname{Pred}(i) ; P, T\rangle & \rightarrow_{\mathrm{c}}\left\langle\vec{R}\left[R_{i}:=\# \mathrm{~A}\right], j \leftarrow \operatorname{Pred}(i) ; P, T\right\rangle \\
\langle\vec{R}, j \leftarrow \operatorname{Succ}(i) ; P, T\rangle & \rightarrow_{\mathrm{c}}\left\langle\vec{R}\left[R_{i}:=\# \mathrm{~A}\right], j \leftarrow \operatorname{Succ}(i) ; P, T\right\rangle \\
\langle\vec{R}, l \leftarrow \operatorname{Test}(i, j, k) ; P, T\rangle & \rightarrow_{\mathrm{c}}\left\langle\vec{R}\left[R_{i}:=\# \mathrm{~A}\right], l \leftarrow \operatorname{Test}(i, j, k) ; P, T\right\rangle
\end{aligned}
$$

Fig. 3. Small-step operational semantics for extended addressing machines.

## 3 Typing Algorithm

Recall that the set $\mathbb{T}$ of (simple) types has been introduced in Definition 1.6(i). We now show that certain EAMs can be typed, and that typable machines do not raise error during their execution.
Definition 3.1 (i) A typing context $\Delta$ is a finite set of associations between registers and types, represented as a list $R_{i_{1}}: \alpha_{1}, \ldots, R_{i_{n}}: \alpha_{n}$. The indices $i_{1}, \ldots, i_{n}$ are not necessarily consecutive.
(ii) We denote by $\Delta\left[R_{i}: \alpha\right]$ the typing context $\Delta$ where the type associated with $R_{i}$ becomes $\alpha$. If $R_{i}$ is not present in $\Delta$, then $\Delta\left[R_{i}: \alpha\right]=\Delta, R_{i}: \alpha$.
(iii) Let $\Delta$ be a typing context, $\mathrm{M} \in \mathcal{M}_{\mathbb{A}}, P$ be a program, $T \in \mathcal{T}_{\mathbb{A}}$ and $\alpha \in \mathbb{T}$. We define the typing judgements

$$
\Delta \vdash \mathrm{M}: \alpha \quad \Delta \Vdash(P, T): \alpha
$$

by mutual induction as the least relations closed under the rules of Figure 4. The rules (nat) and (fix) are the base cases and take precedence over $\left(R_{\varnothing}\right)$ and $\left(R_{\mathbb{T}}\right)$.
(iv) For $R_{i_{1}}, \ldots, R_{i_{n}} \in \vec{R}$, write $R_{i_{1}}: \beta_{i_{1}}, \ldots, R_{i_{n}}: \beta_{i_{n}} \models \vec{R}$ if $\#^{-1}\left(!R_{j}\right): \beta_{j}$, for all $j \in\left\{i_{1}, \ldots, i_{n}\right\}$.

The algorithm in Figure 4 deserves some discussion. As it is presented as a set of inference rules, one should reason bottom-up. To give a machine M a type $\alpha$, one needs to derive the judgement $\vdash \mathrm{M}: \alpha$. The machines n and $\mathrm{Y}_{n}$ are recognizable from their addresses and the rules (nat) and (fix) can thus be given higher precedence. Otherwise, the rule $\left(R_{\mathbb{T}}\right)$ allows to check whether the value in a register is typable and only retain its type, the rule $\left(R_{\varnothing}\right)$ allows to get rid of uninitialized registers. Once this initial step is

$$
\begin{aligned}
& \frac{\# \mathrm{M} \in \mathbb{N}}{\vdash \mathrm{M}: \mathrm{int}} \text { nat } \quad \frac{\# \mathrm{M}=a_{\mathrm{Y}_{n}} \quad \vec{\delta}=\delta_{1} \rightarrow \cdots \rightarrow \delta_{n}}{\vdash \mathrm{M}:(\vec{\delta} \rightarrow \alpha \rightarrow \alpha) \rightarrow \vec{\delta} \rightarrow \alpha} \text { fix }_{n} \quad \frac{\Delta \Vdash(P, T): \alpha}{\Delta \vdash\langle(), P, T\rangle: \alpha} R_{()} \\
& \frac{\Delta \vdash\left\langle R_{0}, \ldots, R_{r-1}, P, T\right\rangle: \alpha \quad!R_{r}=\varnothing}{\Delta \vdash\left\langle\left(R_{0}, \ldots, R_{r}\right), P, T\right\rangle: \alpha} R_{\varnothing} \frac{R_{r}: \beta, \Delta \vdash\left\langle R_{0}, \ldots, R_{r-1}, P, T\right\rangle: \alpha \vdash \#^{-1}\left(!R_{r}\right): \beta}{\Delta \vdash\left\langle\left(R_{0}, \ldots, R_{r}\right), P, T\right\rangle: \alpha} R_{\mathbb{T}} \\
& \frac{\Delta\left[R_{i}: \beta\right] \Vdash(P,[]): \alpha}{\Delta \Vdash(\operatorname{Load} i ; P,[]): \beta \rightarrow \alpha} \operatorname{load}_{\varnothing} \quad \frac{\Delta\left[R_{i}: \beta\right] \Vdash(P, T): \alpha \vdash \#^{-1}(a): \beta}{\Delta \Vdash(\operatorname{Load} i ; P, a:: T): \alpha} \operatorname{load}_{\mathbb{T}} \\
& \frac{\left(\Delta, R_{i}: \operatorname{int}\right)\left[R_{j}: \operatorname{int}\right] \Vdash(P, T): \alpha}{\Delta, R_{i}: \text { int } \Vdash(j \leftarrow \operatorname{Pred}(i) ; P, T): \alpha} \text { pred } \quad \frac{\left(\Delta, R_{i}: \operatorname{int}\right)\left[R_{j}: \operatorname{int}\right] \Vdash(P, T): \alpha}{\Delta, R_{i}: \operatorname{int} \Vdash(j \leftarrow \operatorname{Succ}(i) ; P, T): \alpha} \text { succ } \\
& \frac{\left(\Delta, R_{i}: \text { int }, R_{j}: \beta, R_{k}: \beta\right)\left[R_{l}: \beta\right] \Vdash(P, T): \alpha}{\Delta, R_{i}: \operatorname{int}, R_{j}: \beta, R_{k}: \beta \Vdash(l \leftarrow \operatorname{Test}(i, j, k) ; P, T): \alpha} \text { test } \\
& \frac{\left(\Delta, R_{i}: \alpha \rightarrow \beta, R_{j}: \alpha\right)\left[R_{k}: \beta\right] \Vdash(P, T): \delta}{\Delta, R_{i}: \alpha \rightarrow \beta, R_{j}: \alpha \Vdash(k \leftarrow \operatorname{App}(i, j) ; P, T): \delta} \text { app } \\
& \frac{\vdash \mathrm{M}_{1}: \alpha_{1} \cdots \quad \vdash \mathrm{M}_{n}: \alpha_{n}}{\Delta, R_{i}: \alpha_{1} \rightarrow \cdots \rightarrow \alpha_{n} \rightarrow \alpha \Vdash\left(\text { Call } i,\left[\# \mathrm{M}_{1}, \ldots, \# \mathrm{M}_{n}\right]\right): \alpha} \text { call }
\end{aligned}
$$

Fig. 4. Typing rules for extended addressing machines.
performed, one needs to derive a judgement of the form $R_{i_{1}}: \beta_{i_{1}}, \ldots, R_{i_{n}}: \beta_{i_{n}} \Vdash(P, T): \alpha$, where $P$ and $T$ are the program and the input tape of the original machine respectively. This is done by verifying the coherence of the instructions in the program with the types of the registers and of the values in the input tape. As a final consideration, notice that the rules in Figure 4 can only be considered as an algorithm when the address table map is effectively given. Otherwise, the algorithm would depend on an oracle deciding $a=\# \mathrm{M}$.
Remark 3.2 (i) For all $\mathrm{M} \in \mathcal{M}_{\mathbb{A}}$ and $\alpha \in \mathbb{T}$, we have $\vdash \mathrm{M}: \alpha$ if and only if there exists $a \in \mathbb{A}$ such that both $\#^{-1}(a): \alpha$ and $\# \mathrm{M}=a$ hold.
(ii) If $\# \mathrm{M} \notin \mathbb{N} \cup\left\{a_{Y_{n}} \mid n \geq 0\right\}$, then $\vdash \mathrm{M}: \alpha \Longleftrightarrow \exists \Delta \cdot[\Delta \models \mathrm{M} \cdot \vec{R} \wedge \Delta \Vdash(\mathrm{M} \cdot P, \mathrm{M} \cdot T): \alpha]$
(iii) The higher priority assigned to the rules (nat) and (fix) does not modify the set of typable machines, rather guarantees the syntax-directedness of the system.

Example 3.3 The following typing judgements are derivable.
(i) $\vdash$ Succ2 : int $\rightarrow$ int
(ii) $\vdash$ Add : int $\rightarrow$ int $\rightarrow$ int, where Add $=\mathrm{Y}_{0}$ @ [\#Add_aux]
(iii) For a smaller example, like $\vdash$ Succ1 : int $\rightarrow$ int, we can provide the whole derivation tree:

Lemma 3.4 Let $\mathrm{M} \in \mathcal{M}_{\mathbb{A}}, \alpha \in \mathbb{T}$. Assume that $\#: \mathrm{M} \rightarrow \mathbb{A}$ is effectively given.
(i) If $\mathrm{M}=\langle\vec{R}=\varnothing, P,[]\rangle$ then the typing algorithm is capable of deciding whether $\vdash \mathrm{M}: \alpha$ holds.
(ii) In general, the typing algorithm semi-decides whether $\vdash \mathrm{M}: \alpha$ holds.

Proof. (Sketch) (i) In this case, $\vdash \mathrm{M}: \alpha$ holds if and only if $\Vdash(\mathrm{M} . P,[])$ does. By induction on the length of M.P, one verifies if it is possible to construct a derivation. Otherwise, conclude that $\vdash \mathrm{M}: \alpha$ is not
derivable.
(ii) In the rules $\left(R_{\mathbb{T}}\right)$ and $\left(\operatorname{load}_{\mathbb{T}}\right)$, one needs to show that a type for the premises exists. As the set of types is countable, and effectively given, one can easily design an algorithm constructing a derivation tree (by dovetailing). However, the algorithm cannot terminate when executed on $\mathrm{M}_{0}$ from Remark 2.9.

The machine $\mathrm{M}_{0}$ in Remark 2.9 cannot be typable because it would require an infinite derivation tree.
Proposition 3.5 Let $\mathrm{M}, \mathrm{M}^{\prime}, \mathrm{N}, \in \mathcal{M}_{\mathbb{A}}$ and $\alpha, \beta \in \mathbb{T}$.
(i) If $\vdash \mathrm{M}: \beta \rightarrow \alpha$ and $\vdash \mathrm{N}: \beta$ then $\vdash \mathrm{M} @[\# \mathrm{~N}]: \alpha$.
(ii) If $\vdash \mathrm{M}: \alpha$ and $\mathrm{M} \rightarrow_{c} \mathrm{~N}$ then $\vdash \mathrm{N}: \alpha$.
(iii) If $\vdash \mathrm{M}$ : int then either M does not terminate or $\mathrm{M} \rightarrow{ }_{c} \mathrm{n}$, for some $n \geq 0$.
(iv) If $\vdash \mathrm{M}: \alpha$ then M does not raise an error.

Proof. (i) Simultaneously, one proves that $\Delta \Vdash(P, T): \beta \rightarrow \alpha$ and $\vdash \mathrm{N}: \beta$ imply $\Delta \Vdash(P, T @[\# \mathrm{~N}]): \alpha$. Proceed by induction on a derivation of $\vdash \mathrm{M}: \beta \rightarrow \alpha($ resp. $\Delta \Vdash(P, T): \beta \rightarrow \alpha)$.

Case (nat) is vacuous.
Case ( $\mathrm{fix}_{\mathrm{n}}$ ). We show the case for $n=0$, the others being similar. By definition of $\mathrm{Y}_{0}$, we have:

$$
\mathrm{Y}_{0} @[\# \mathrm{~N}]=\left\langle\left(\varnothing, a_{\mathrm{Y}_{0}}\right), \text { Load } 0 ; 1 \leftarrow \operatorname{App}(1,0) ; 0 \leftarrow \operatorname{App}(0,1) ; \text { Call } 0,[\# \mathrm{~N}]\right\rangle .
$$

Notice that, in this case, $\beta=\alpha \rightarrow \alpha$. Using $\#^{-1}\left(a_{Y_{0}}\right)=\mathrm{Y}_{0}$, we derive:

Case load $\varnothing$. Then $P=$ Load $i ; P^{\prime}, T=[]$ and $\Delta\left[R_{i}: \beta\right] \Vdash\left(P^{\prime},[]\right): \alpha$. By assumption $\vdash \mathrm{N}: \beta$, so we conclude $\Delta \Vdash\left(\operatorname{Load} i ; P^{\prime},[]\right): \alpha$ by applying load $\mathbb{T}_{\mathbb{T}}$. All other cases derive straightforwardly from the IH .
(ii) The cases $\mathrm{M}=\mathrm{Y}_{n}$ or $\mathrm{M}=\mathrm{n}$ for some $n \in \mathbb{N}$ are vacuous, as these machines are in final state. Otherwise, by Remark 3.2(ii), $\Delta \Vdash(\mathrm{M} . P, \mathrm{M} . T): \alpha$ for some $\Delta \models \mathrm{M} . \vec{R}$. By cases on the shape of M.P.

Case $P=$ Load $i ; P^{\prime}$. Then M. $T=a:: T^{\prime}$ otherwise M would be in final state, and $\mathrm{N}=\left\langle\vec{R}\left[R_{i}:=\right.\right.$ a], $\left.P^{\prime}, T^{\prime}\right\rangle$. From $\left(\operatorname{Load}_{\mathbb{T}}\right)$ we get $\Delta\left[R_{i}: \beta\right] \Vdash\left(P^{\prime}, T^{\prime}\right): \alpha$ for some $\beta \in \mathbb{T}$ satisfying $\#^{-1}(a): \beta$. As $\Delta \models \vec{R}$ we derive $\Delta\left[R_{i}: \beta\right] \models \vec{R}\left[R_{i}:=a\right]$, so as $N=\left\langle\vec{R}\left[R_{i}:=a\right], P^{\prime}, T^{\prime}\right\rangle$, by Remark 3.2(ii), $\vdash N: \alpha$.

Case $P=$ Call $i$. Then $R_{i}: \alpha_{1} \rightarrow \cdots \rightarrow \alpha_{n} \rightarrow \alpha, T=\left[\# \mathrm{M}_{1}, \ldots, \# \mathrm{M}_{n}\right]$ and $\vdash \mathrm{M}_{j}: \alpha_{j}$, for all $j \leq n$. In this case, $\mathrm{N}=\#^{-1}\left(!\left(\mathrm{M} \cdot R_{i}\right)\right) @ T$ with $\vdash \#^{-1}\left(!\left(\mathrm{M} \cdot R_{i}\right)\right): \alpha_{1} \rightarrow \cdots \rightarrow \alpha_{n} \rightarrow \alpha$, so we conclude by (i).

All other cases follows easily from the IH.
(iii) Assume that $\vdash \mathrm{M}$ : int and $\mathrm{M} \rightarrow{ }_{c} \mathrm{~N}$ for some N in final state. By (ii), we obtain that $\vdash \mathrm{N}$ : int holds, therefore $\mathrm{N}=\mathrm{n}$ since numerals are the only machines in final state typable with int.
(iv) The three cases from Figure 3 where a machine can raise an error are ruled out by the typing rules (pred), (succ) and (test), respectively. Therefore, no error can be raised during the execution.

## 4 Translation and Simulation

We define a type-preserving translation from EPCF terms to extended addressing machines. More precisely, we show that if $\Gamma \vdash^{\mathrm{E}} M: \alpha$ is derivable then $M$ is transformed into a machine M which is typable with the same $\alpha$. By Proposition 3.5, M never raises a runtime error and well-typedness is preserved during its execution. We then show that if a well-typed EPCF program $M$ computes a value $\underline{n}$, then its translation

M reduces to the corresponding EAM n. Finally, this result is transported to PCF using their equivalence on programs of type int.

We start by showing that EAMs implementing the main PCF instructions are definable. We do not need any machinery for representing explicit substitutions because they are naturally modelled by the evaluation strategy of EAMs.

Lemma 4.1 Let $n \geq 0$. There are EAMs satisfying (for all $a, b, c, d_{1}, \ldots, d_{n} \in \mathbb{A}$ ):
(i) $\operatorname{Pr}_{i}^{n} @\left[d_{1}, \ldots, d_{n}\right] \quad \rightarrow_{c} d_{i}$, for $1 \leq i \leq n$;
(ii) Apply ${ }_{n} @\left[a, b, d_{1}, \ldots, d_{n}\right] \rightarrow{ }_{\mathrm{c}} \#^{-1}(a) @\left[d_{1}, \ldots, d_{n}, b \cdot d_{1} \cdots d_{n}\right]$;
(iii) $\operatorname{Pred}_{n} @\left[a, d_{1}, \ldots, d_{n}\right] \rightarrow{ }_{c}\left\langle R_{0}=a \cdot d_{1} \cdots d_{n}, \vec{R}, ; 0 \leftarrow \operatorname{Pred}(0) ;\right.$ Call $\left.0,[]\right\rangle$;
(iv) $\mathrm{Succ}_{n} @\left[a, d_{1}, \ldots, d_{n}\right] \rightarrow{ }_{c}\left\langle R_{0}=a \cdot d_{1} \cdots d_{n}, \vec{R} ; ; 0 \leftarrow \operatorname{Succ}(0) ; \operatorname{Call} 0,[]\right\rangle$;
(v) $\mathrm{Ifz}_{n} @\left[a, b, c, d_{1}, \ldots, d_{n}\right] \rightarrow_{\mathrm{c}}\left\langle R_{0}=a \cdot \vec{d}, R_{1}=b \cdot \vec{d}, R_{2}=c \cdot \vec{d}, \vec{R}, 0 \leftarrow\right.$ Test $(0,1,2) ;$ Call $\left.0,[]\right\rangle$.

Proof. Easy. As an example, we give a possible definition of the predecessor:

$$
\operatorname{Pred}_{n}=\left\langle R_{0}, \ldots, R_{n}, \operatorname{Load}(0, \ldots, n) ; 0 \leftarrow \operatorname{App}(0,1) ; \cdots ; 0 \leftarrow \operatorname{App}(0, n) ; 0 \leftarrow \operatorname{Pred}(0) ; \operatorname{Call} 0,[]\right\rangle
$$

The others are similar.
Lemma 4.2 The EAMs in the previous lemma can be defined in order to ensure their typability (for all $\left.n \geq 0, \alpha, \beta, \gamma, \delta_{i} \in \mathbb{T}\right)$ :
(i) $\vdash \operatorname{Pr}_{i}^{n}: \vec{\delta} \rightarrow \delta_{i}$, with $\vec{\delta}=\delta_{1} \rightarrow \cdots \rightarrow \delta_{n}$;
(ii) $\vdash$ Apply $_{n}:(\vec{\delta} \rightarrow \beta \rightarrow \alpha) \rightarrow(\vec{\delta} \rightarrow \beta) \rightarrow \vec{\delta} \rightarrow \alpha$;
(iii) $\vdash \operatorname{Pred}_{n}:(\vec{\delta} \rightarrow$ int $) \rightarrow \vec{\delta} \rightarrow$ int;
(iv) $\vdash$ Succ $_{n}:(\vec{\delta} \rightarrow$ int $) \rightarrow \vec{\delta} \rightarrow$ int;
(v) $\vdash \mathrm{Ifz}_{n}:(\vec{\delta} \rightarrow \mathrm{int}) \rightarrow(\vec{\delta} \rightarrow \alpha) \rightarrow(\vec{\delta} \rightarrow \alpha) \rightarrow \vec{\delta} \rightarrow \alpha ;$

Proof. The naive implementations are, in fact, typable.
We will show that, using the auxiliary EAMs given in Lemma 4.2, we can translate any EPCF term into an EAM. In order to proceed by induction, we first need to define the size of an EPCF term.

Definition 4.3 Let $M$ be an EPCF term and $\sigma$ be an explicit substitution. The sizes $|-|$ of $\sigma, M$ and $(\sigma, M)$ are defined by mutual induction, e.g.

$$
\begin{aligned}
|[]| & =0, & |(\sigma, M)| & =|\sigma|+|M|, \\
\left|\rho+\left[x \leftarrow\left(\rho^{\prime}, N\right)\right]\right| & =|\rho|+\left|\left(\rho^{\prime}, N\right)\right|, & |\lambda x . M\langle\sigma\rangle| & =|(\sigma, M)|+1,
\end{aligned}
$$

and the other cases of $|M|$ are standard whence they are omitted.
Intuitively, an EPCF term $M$ having $x_{1}, \ldots, x_{n}$ as free variables is translated as an EAM M loading $n$ arguments as input.
Definition 4.4 (Translation) Let $M$ be an EPCF term and $\sigma$ be an explicit substitution such that $\mathrm{FV}(M) \subseteq \operatorname{dom}(\sigma) \cup\{\vec{x}\}$, where $\vec{x}=x_{1}, \ldots, x_{n}$. The translation of the pair $(\sigma, M)$ (w.r.t $\vec{x}$ ) is a machine denoted $(\sigma, M)^{\vec{x}} \in \mathcal{M}_{\mathbb{A}}$, or simply $\llbracket M \rrbracket^{\vec{x}}$ when $\sigma$ is empty. ${ }^{7}$ The machine $(\sigma, M\rangle^{\vec{x}}$ is defined by

[^2]induction on $|(\sigma, M)|$ as follows:
\[

$$
\begin{array}{ll}
(\sigma+[y \leftarrow(\tau, N)], M)^{\vec{x}} & =(\sigma, M)^{y, \vec{x}} @[\# \backslash \tau, N D] ; \\
\llbracket x i \rrbracket^{\vec{x}} & =\operatorname{Pr}_{i}^{n}, \\
\llbracket \lambda y \cdot M\langle\sigma\rangle \rrbracket^{\vec{x}} & =\left(\sigma, M \downarrow^{\vec{x}, y}, \text { where wlog } y \notin \vec{x} ;\right. \\
\llbracket M \cdot N \rrbracket^{\vec{x}} & =\operatorname{Apply}_{n} @\left[\# \llbracket M \rrbracket^{\vec{x}}, \# \llbracket N \rrbracket^{\vec{x}}\right] ; \\
\llbracket \underline{k} \rrbracket^{\vec{x}} & =\operatorname{Pr}_{1}^{n+1} @[k], \text { where } k \in \mathbb{N} ; \\
\llbracket \operatorname{pred} M \rrbracket^{\vec{x}} & =\operatorname{Pred}_{n} @\left[\# \llbracket M \rrbracket^{\vec{x}}\right] ; \\
\llbracket \operatorname{succ} M \rrbracket^{\vec{x}} & =\operatorname{Succ}_{n} @\left[\# \llbracket M \rrbracket^{\vec{x}}\right] ; \\
\llbracket \operatorname{ifz}(L, M, N) \rrbracket^{\vec{x}} & =\operatorname{Ifz}_{n} @\left[\# \llbracket L \rrbracket^{\vec{x}}, \# \llbracket M \rrbracket^{\vec{x}}, \# \llbracket N \rrbracket^{\vec{x}}\right] ; \\
\llbracket \operatorname{fix} M \rrbracket^{\vec{x}} & =\mathrm{Y}_{n} @\left[\# \llbracket M \rrbracket^{\vec{x}}\right] .
\end{array}
$$
\]

We show the extended abstract machines associated by this translation to some of our running examples.
Example 4.5 1. $\llbracket\left(\lambda x \cdot \operatorname{succ}(x)\rangle) \cdot \underline{0} \rrbracket=\operatorname{Succ}_{1} @\left[\# \operatorname{Pr}_{1}^{1}, 0\right]\right.$.
2. $\llbracket(\lambda s n \cdot s(s n))(\lambda x$.succ $(x)) \rrbracket=$ Apply $_{2} @\left[\# \operatorname{Pr}_{1}^{2}, \#\left(\right.\right.$ Apply $\left._{2} @\left[\# \operatorname{Pr}_{1}^{2}, \# \operatorname{Pr}_{2}^{2}\right]\right)$, \#(Succ $\left.\left.@\left[\# \operatorname{Pr}_{1}^{1}\right]\right)\right]$.
3. $\llbracket \mathbf{a d d} \rrbracket=\mathrm{Y}_{0} @ \# \llbracket \lambda f x y . \mathbf{i f z}(y, x,(f \cdot(\operatorname{succ} x) \cdot(\operatorname{pred} y))) \rrbracket$

$$
\begin{aligned}
& =\mathrm{Y}_{0} @ \# \llbracket \operatorname{ifz}(y, x,(f \cdot(\operatorname{succ} x) \cdot(\operatorname{pred} y))) \rrbracket^{f, x, y}, \\
& =\mathrm{Y}_{0} @ \#\left(\mathrm{Ifz}_{3} @\left[\# \operatorname{Pr}_{3}^{3}, \# \operatorname{Pr}_{2}^{3}, \# \llbracket f \cdot(\operatorname{succ} x) \cdot(\operatorname{pred} y) \rrbracket^{f, x, y}\right]\right),
\end{aligned}
$$

where $\llbracket f \cdot(\mathbf{s u c c} x) \cdot(\mathbf{p r e d} y) \rrbracket^{f, x, y}=\operatorname{Apply}_{3} @\left[\#\left(\right.\right.$ Apply $_{3} @\left[\# \operatorname{Pr}_{1}^{3}, \#\left(\right.\right.$ Succ $\left.\left.\left._{3} @\left[\# \operatorname{Pr}_{2}^{3}\right]\right)\right]\right)$, \#( $\left.\left.\operatorname{Pred}_{3} @\left[\# \operatorname{Pr}_{3}^{3}\right]\right)\right]$.
Theorem 4.6 Let $M$ be an EPCF term, $\alpha \in \mathbb{T}, \Gamma=x_{1}: \beta_{1}, \ldots, x_{n}: \beta_{n}$. Then

$$
\Gamma \vdash^{\mathrm{E}} M: \alpha \Rightarrow \vdash \llbracket M \rrbracket^{x_{1}, \ldots, x_{n}}: \beta_{1} \rightarrow \cdots \rightarrow \beta_{n} \rightarrow \alpha
$$

Proof. By induction on a derivation of $\Gamma \vdash^{\mathrm{E}} M: \alpha$. As an induction loading, one needs to prove simultaneously that for all explicit substitutions $\sigma$ with $\operatorname{dom}(\sigma)=\left\{x_{1}, \ldots, x_{n}\right\}$, if $\sigma \models x_{1}: \beta_{1}, \ldots, x_{n}: \beta_{n}$ then $\vdash\left(\sigma\left(x_{i}\right)\right): \beta_{i}$, for all $i \leq n$.

Theorem 4.7 Let $M$ be an EPCF term and $V \in$ Val. Then

$$
\sigma \triangleright M \Downarrow_{d} V \Rightarrow\left(\sigma, M D \leftrightarrow_{c} \llbracket V \rrbracket\right.
$$

Proof. By induction on a derivation of $\sigma \triangleright M \Downarrow_{d} V$.
Corollary 4.8 For an EPCF program $M$ of type $\vdash^{\mathrm{E}} M$ : int we have

$$
[] \triangleright M \Downarrow_{d} \underline{n} \Rightarrow \llbracket M \rrbracket \rightarrow_{c} \mathrm{n}
$$

Proof. Assume that [] $M \Downarrow_{d} \underline{n}$. By Theorem 4.7, we have $([], M) \leftrightarrow_{c} \llbracket \underline{n} \rrbracket$. Since $\llbracket \underline{n} \rrbracket \rightarrow_{c} \mathrm{n}$ and the numeral machine n is in final state we conclude $\llbracket M \rrbracket \rightarrow_{\mathrm{c}} \mathrm{n}$.

### 4.1 Applying the translation to regular PCF

Let us show how to apply our machinery to the usual (call-by-name) PCF. Our presentation follows [22].

$$
\begin{array}{ccc}
\frac{U \in \mathrm{Val}}{U \Downarrow U}(\text { val }) & \frac{P \Downarrow \mathbf{0}}{\operatorname{pred} P \Downarrow \mathbf{0}}\left(\mathrm{pr}_{0}\right) & \frac{P \Downarrow \underline{n+1}}{\operatorname{pred} P \Downarrow \underline{n}}(\mathrm{pr}) \\
\frac{P \Downarrow \underline{0} \quad Q \Downarrow U_{1}}{\operatorname{ifz}\left(P, Q, Q^{\prime}\right) \Downarrow U_{1}}\left(\mathrm{ifz} z_{0}\right) & \frac{P \Downarrow \underline{n+1} Q^{\prime} \Downarrow U_{2}}{\operatorname{ifz}\left(P, Q, Q^{\prime}\right) \Downarrow U_{2}}\left(\mathrm{ifz}_{>0}\right) \frac{P \Downarrow \underline{n}}{\text { succ } P \Downarrow \underline{n+1}}(\mathrm{sc}) \\
\frac{P \cdot(\mathrm{fix} P) \Downarrow U}{\text { fix } P \Downarrow U}(\text { fix }) & \frac{P \Downarrow \lambda x \cdot P^{\prime} \quad P^{\prime}[Q / x] \Downarrow U}{P \cdot Q \Downarrow U}\left(\beta_{v}\right)
\end{array}
$$

Fig. 5. The big-step operational semantics of PCF.

$$
\begin{array}{ccccc}
\overline{\Gamma, x: \alpha \vdash x: \alpha} & \frac{\Gamma, x: \alpha \vdash P: \beta}{\Gamma \vdash \lambda x . P: \alpha \rightarrow \beta} & \overline{\Gamma \vdash 0: \text { int }} & \frac{\Gamma \vdash P: \alpha \rightarrow \beta \quad \Gamma \vdash Q: \alpha}{\Gamma \vdash P Q: \beta} \\
\frac{\Gamma \vdash P: \operatorname{int}}{\Gamma \vdash \text { pred } P: \text { int. }} & \frac{\Gamma \vdash P: \alpha \rightarrow \alpha}{\Gamma \vdash \text { fix } P: \alpha} & \frac{\Gamma \vdash P: \operatorname{int}}{\Gamma \vdash \operatorname{succ} P: \text { int. }} & \frac{\Gamma \vdash P: \operatorname{int} \Gamma \vdash Q: \alpha \quad \Gamma \vdash Q^{\prime}: \alpha}{\Gamma \vdash \operatorname{ifz}\left(P, Q, Q^{\prime}\right): \alpha}
\end{array}
$$

Fig. 6. The type inference rules of PCF.

Definition 4.9 (i) PCF terms are defined by the grammar (for $n \geq 0, x \in \operatorname{Var}$ ):

$$
P, Q, Q^{\prime}::=x|P \cdot Q| \lambda x . P|\mathbf{0}| \operatorname{pred} P|\operatorname{succ} P| \operatorname{ifz}\left(P, Q, Q^{\prime}\right) \mid \text { fix } P
$$

(ii) A closed PCF term $P$ is called a PCF program.
(iii) A PCF value $U$ is a term of the form $\lambda x . P$ or $\underline{n}$, for some $n \geq 0$.
(iv) Given a PCF term $P$ and a value $U$, we write $P \Downarrow U$ if this judgement can be obtained by applying the rules from Figure 5.
(v) The set $\mathbb{T}$ of simple types and typing contexts have already been defined in items (i) and (ii) of Definition 1.6, respectively.
(vi) Given a PCF term $P$, a typing context $\Gamma$ and $\alpha \in \mathbb{T}$, we write $\Gamma \vdash^{\text {PCF }} P$ : $\alpha$ if this typing judgement is derivable from the rules of Figure 6.

Recall that any PCF program $P$ can be seen as an EPCF term, thanks to the notation $\lambda x \cdot N:=\lambda x \cdot N\langle \rangle$. However, the hypotheses $\vdash^{\text {PCF }} P$ : int and $P \Downarrow \underline{n}$ are a priori not sufficient for applying Corollary 4.8, since one needs to show that also the corresponding EPCF judgments $\vdash^{\mathrm{E}} P$ : int and $P \Downarrow_{d} \underline{n}$ hold. The former is established by the following lemma.

Lemma 4.10 Let $M$ be a PCF term, $\alpha \in \mathbb{T}$ and $\Gamma$ be a context. Then

$$
\Gamma \vdash^{\mathrm{PCF}} M: \alpha \quad \Rightarrow \quad \Gamma \vdash^{\mathrm{E}} M: \alpha
$$

Proof. By a straightforward induction on a derivation of $\Gamma \vdash^{\text {PCF }} M$.
An EPCF term is easily translated into PCF by performing all its explicit substitutions. The converse is trickier as the representation is not unique: for every PCF term $P$ there are several decompositions $P=P^{\prime}\left[Q_{1} / x_{1}, \ldots, Q_{n} / x_{n}\right]$. Recall that the size $|(\sigma, M)|$ has been defined in Definition 4.3.

Definition 4.11 Let $M$ be an EPCF term and $\sigma$ be an explicit substitution. Define a PCF term $(\sigma, M)^{*}$
by induction on $|(\sigma, M)|$ as follows:

$$
\begin{aligned}
(\sigma, x)^{*} & = \begin{cases}\sigma(x)^{*}, & \text { if } x \in \operatorname{dom}(\sigma), \\
x, & \text { otherwise },\end{cases} \\
(\sigma, \lambda x \cdot M\langle\rho\rangle)^{*} & =\lambda x \cdot(\sigma+\rho, M)^{*}, \\
(\sigma, M \cdot N)^{*} & =(\sigma, M)^{*} \cdot(\sigma, N)^{*}, \\
(\sigma, \operatorname{fix} M)^{*} & =\operatorname{fix}\left((\sigma, M)^{*}\right), \\
(\sigma, \underline{0})^{*} & =\underline{0}, \\
(\sigma, \operatorname{pred} M)^{*} & =\operatorname{pred}(\sigma, M)^{*}, \\
(\sigma, \operatorname{succ} M)^{*} & =\operatorname{succ}(\sigma, M)^{*}, \\
(\sigma, \operatorname{ifz}(L, M, N))^{*} & =\operatorname{ifz}\left((\sigma, L)^{*},(\sigma, M)^{*},(\sigma, N)^{*}\right) .
\end{aligned}
$$

For a PCF term $P$, define $P^{\dagger}=\left\{(\sigma, M) \mid(\sigma, M)^{*}=P\right\}$.
To show the equivalence between PCF and EPCF, we need yet another auxiliary lemma.

## Lemma 4.12 (Substitution Lemma)

(i) Let $M, N$ be EPCF terms, $\sigma, \rho$ be explicit substitutions and $x$ be a variable.

$$
(\sigma+[x \leftarrow(\rho, N)], M)^{*}=(\sigma, M)^{*}\left[(\rho, N)^{*} / x\right]
$$

(ii) Let $P, Q$ be PCF terms with $\mathrm{FV}(P) \subseteq\{x\}$ and $Q$ closed. For all EPCF terms $M, N$ and explicit substitutions $\sigma, \rho$, we have:

$$
(\sigma, M) \in P^{\dagger} \wedge(\rho, N) \in Q^{\dagger} \Rightarrow(\sigma+[x \leftarrow(\rho, N)], M) \in(P[Q / x])^{\dagger}
$$

We rely on the freshness hypothesis on the variables in $\operatorname{dom}(\sigma)$.
Proof. (i) By structural induction on $M$.
Case $M=y$, with $y \neq x$ : There are two subcases.

- If $y \in \operatorname{dom}(\sigma)$, then $(\sigma+[x \leftarrow(\rho, N)], y)^{*}=\sigma(y)=\sigma(y)\left[(\rho, N)^{*} / x\right]=(\sigma, y)^{*}\left[(\rho, N)^{*} / x\right]$, since $x \notin \mathrm{FV}(\sigma(y))$;
- if $y \notin \operatorname{dom}(\sigma)$, then $(\sigma+[x \leftarrow(\rho, N)], y)^{*}=y=y\left[(\rho, N)^{*} / x\right]=(\sigma, y)^{*}\left[(\rho, N)^{*} / x\right]$.

Case $M=x$ : Then $(\sigma+[x \leftarrow(\rho, N)], x)^{*}=(\rho, N)^{*}=x\left[(\rho, N)^{*} / x\right]=(\sigma, x)^{*}\left[(\rho, N)^{*} / x\right]$.
Case $M=\lambda y \cdot M^{\prime}$ : Wlog, we may assume $y \neq x$. We have $\left(\sigma+[x \leftarrow(\rho, N)], \lambda y \cdot M^{\prime}\right)^{*}=\lambda y \cdot(\sigma+[x \leftarrow$ $\left.(\rho, N)], M^{\prime}\right)^{*}=\lambda y \cdot\left(\left(\sigma, M^{\prime}\right)^{*}\left[(\rho, N)^{*} / x\right]\right)=\left(\lambda y \cdot\left(\sigma, M^{\prime}\right)^{*}\right)\left[(\rho, N)^{*} / x\right]=\left(\left(\sigma, \lambda y \cdot M^{\prime}\right)^{*}\right)\left[(\rho, N)^{*} / x\right]$.
All other cases derive straightforwardly from the IH.
(ii) By an easy induction on $P$, using (i).

Theorem 4.13 The big-step weak reduction of EPCF is equivalent to the usual big-step operational semantics of PCF. Formally:
(i) Given an EPCF program $M$, a value $V$ and an explicit substitution $\sigma$, we have:

$$
\sigma \triangleright M \Downarrow_{d} V \quad \Rightarrow \quad(\sigma, M)^{*} \Downarrow([], V)^{*}
$$

(ii) Given a PCF program $P$ and PCF value $U$. If $P \Downarrow U$ then

$$
\forall(\sigma, M) \in P^{\dagger}, \exists V \in \operatorname{Val} .\left(\sigma \triangleright M \Downarrow_{d} V \text { and }([], V) \in U^{\dagger}\right)
$$

Proof. (Proof sketch) For the full proof, we refer to the technical Appendix A.
(i) Proceed by induction on a derivation of $\sigma \triangleright M \Downarrow_{d} V$, using Lemma 4.12(i) in the ( $\beta_{v}$ )-case.
(ii) By induction on the lexicographically ordered pairs, whose first component is the length of a derivation of $P \Downarrow U$ and second component is $|(\sigma, M)|$, using Lemma 4.12(ii) in the $\left(\beta_{v}\right)$-case.

As promised, we now draw conclusions for the regular PCF. As customary in PCF, we are interested on the properties of closed terms having ground type.
Theorem 4.14 For a PCF program $P$ of type int, $P \Downarrow \underline{n}$ entails $\llbracket P \rrbracket \rightarrow{ }_{c} \mathrm{n}$.
Proof. Note that $P$ is also an EPCF term such that $([], P) \in P^{\dagger}$, and that $\vdash^{\mathrm{E}} P$ : int by Lemma 4.10. Thus [] $\triangleright P \Downarrow_{d} \underline{n}$ by Theorem 4.13(ii). Conclude by Corollary 4.8.

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## A Technical Appendix

This technical appendix is devoted to provide the proofs that have been partially given, or completely omitted, in the body of the paper. As an abbreviation, we write IH for "induction hypothesis".

## A. 1 Proofs of Section 1

Proof. [Proof of Lemma 1.8] Items (i) and (ii) are straightforward. We prove (iii).
Given an EPCF term $M$, an EPCF value $V$, an explicit substitution $\sigma$, a type $\alpha$, and a context $\Gamma$ such that $\sigma \triangleright M \Downarrow_{d} V, \sigma \models \Gamma, \Gamma \vdash M: \alpha$, we prove by induction on a derivation of $\sigma \triangleright M \Downarrow_{d} V$ that $\vdash V: \alpha$.
Case (nat): In this case $M=V=\underline{n}$, for $\underline{n} \in \mathbb{N}$, and $\alpha=$ int. By the typing rules of EPCF, $\vdash \underline{n}$ : int.
Case (fun): In this case $M=\lambda x \cdot M^{\prime}\langle\rho\rangle, V=\lambda x \cdot M^{\prime}\langle\sigma+\rho\rangle, \alpha=\beta \rightarrow \gamma$. As $\Gamma \vdash \lambda x \cdot M^{\prime}\langle\rho\rangle: \beta \rightarrow \gamma, \exists!\Delta$ such that $\rho \models \Delta, \Gamma, \Delta, x: \beta \vdash M^{\prime}: \gamma$. As $\sigma \models \Gamma$ and $\rho \models \Delta, \sigma+\rho \models \Gamma, \Delta$. Thus by the typing rules of EPCF, $\vdash \lambda x \cdot M^{\prime}\langle\sigma+\rho\rangle: \beta \rightarrow \gamma$.
Case (var): In this case $M=x, \sigma(x)=(\rho, N), \Gamma=\Gamma^{\prime}, x: \alpha$. By the operational semantics of EPCF, $\rho \triangleright N \Downarrow_{d} V$, and by the type system of EPCF as $\sigma \models \Gamma^{\prime}, x: \alpha,[x \leftarrow(\rho, N)] \models x: \alpha$ and thus $\rho \models \Delta, \Delta \vdash N: \alpha$. By IH, $\vdash V: \alpha$.

Case $\left(\beta_{v}\right)$ : In this case $M=N \cdot L$. By the operational semantics of EPCF, $\sigma \triangleright N \Downarrow_{d} \lambda x . N^{\prime}\langle\rho\rangle$ and $\rho+[x \leftarrow(\sigma, L)] \triangleright N^{\prime} \Downarrow_{d} V$. By the type system of EPCF, $\Gamma \vdash N: \beta \rightarrow \alpha, \Gamma \vdash L: \beta$. By IH, $\vdash \lambda x \cdot N^{\prime}\langle\rho\rangle: \beta \rightarrow \alpha$, and then by the type system of EPCF $\rho \models \Delta, \Delta, x: \beta \vdash N^{\prime}: \alpha$. By the type system we also have $[x \leftarrow(\sigma, L)] \models x: \beta$, so $\rho+[x \leftarrow(\sigma, L)] \models \Delta, x: \beta$, and thus by IH we conclude $\vdash V: \alpha$.
All other cases derive straightforwardly from applying the rules of the type system and the IH.

## A. 2 Proofs of Section 4

Proof. [Proof of Theorem 4.6] We prove the following statements by mutual induction and call the respective inductive hypotheses IH 1 and IH 2 .
(i) Let $M$ be an EPCF term, $\Gamma=x_{1}: \beta_{1}, \ldots, x_{n}: \beta_{n}$ and $\alpha \in \mathbb{T}$. Then $\Gamma \vdash M: \alpha \quad \Rightarrow \vdash \llbracket M \rrbracket^{x_{1}, \ldots, x_{n}}:$ $\beta_{1} \rightarrow \cdots \rightarrow \beta_{n} \rightarrow \alpha$.
(ii) For all $\Gamma=x_{1}: \beta_{1}, \ldots, x_{n}: \beta_{n}$ and $\sigma$, with $\operatorname{dom}(\sigma)=\left\{x_{1}, \ldots, x_{n}\right\}$, we have $\sigma \models \Gamma \quad \Rightarrow \vdash\left(\sigma\left(x_{1}\right)\right)$ : $\beta_{1}, \ldots, \vdash\left(\sigma\left(x_{n}\right)\right): \beta_{n}$.
We start with the cases concerning (i).
Case (ax): Then, $x_{1}: \beta_{1}, \ldots, x_{n}: \beta_{n} \vdash x_{i}: \beta_{i}$, and $\llbracket x_{i} \rrbracket^{x_{1}, \ldots, x_{n}}=\operatorname{Pr}_{i}^{n}$. By Lemma 4.2(i) we conclude $\vdash \operatorname{Pr}_{i}^{n}: \beta_{1} \rightarrow \cdots \rightarrow \beta_{n} \rightarrow \beta_{i}$.

Case (0): In this case, we have $\Gamma \vdash \mathbf{0}$ : int and $\llbracket \mathbf{0} \rrbracket^{x_{1}, \ldots, x_{n}}=\operatorname{Pr}_{1}^{n+1} @[0]$. By Lemma 4.2(i) $\vdash \operatorname{Pr}_{1}^{n+1} @$ : int $\rightarrow \beta_{1} \rightarrow \cdots \rightarrow \beta_{n} \rightarrow$ int and, by Figure $4 \vdash \#^{-1}(0):$ int. By Proposition 3.5(i), $\vdash \operatorname{Pr}_{1}^{n+1} @[0]:$ $\beta_{1} \rightarrow \cdots \rightarrow \beta_{n} \rightarrow$ int.

Case (Y): In this case $\Gamma \vdash \mathrm{fix} M^{\prime}: \alpha$ and $\llbracket$ fix $M^{\prime} \rrbracket^{\vec{x}}=\mathrm{Y}_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{\vec{x}}\right]$. By (fix ${ }_{n}$ ) in Figure 4, we have $\vdash \mathrm{Y}_{n}:(\vec{\beta} \rightarrow \alpha \rightarrow \alpha) \rightarrow \vec{\beta} \rightarrow \alpha$. From the hypothesis IH1, we obtain $\vdash \llbracket M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}: \vec{\beta} \rightarrow \alpha \rightarrow \alpha$. By Proposition 3.5(i), we conclude that $\vdash \mathrm{Y}_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}\right]: \beta_{1} \rightarrow \cdots \rightarrow \beta_{n} \rightarrow \alpha$.

Case $(+)$ : In this case $\Gamma \vdash \operatorname{succ} M^{\prime}$ : int since $\Gamma \vdash M^{\prime}:$ int. By definition, $\llbracket \operatorname{succ} M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}=$ Succ $_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}\right]$. By Lemma 4.2(iv), $\vdash$ Succ $_{n}:(\vec{\beta} \rightarrow$ int $) \rightarrow \vec{\beta} \rightarrow$ int. From IH1, we get $\vdash \llbracket M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}: \vec{\beta} \rightarrow \mathrm{int}$, and thus by Proposition 3.5(i), we conclude $\vdash \mathrm{Succ}_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}\right]: \vec{\beta} \rightarrow$ int.
Case (-): Analogous, applying Lemma 4.2(iv).
Case (ifz): Assume $\Gamma \vdash \operatorname{ifz}\left(L, N_{1}, N_{2}\right): \alpha$ since $\Gamma \vdash L$ : int and $\Gamma \vdash N_{i}: \alpha$, for $i \in\{1,2\}$. By definition of the translation, we have $\left.\llbracket \mathrm{ifz}\left(L, N_{2}, N_{2}\right) \rrbracket_{\vec{x}}=1 \mathrm{fz}_{n} @\left[\# \llbracket L \rrbracket^{\vec{x}}, \# \llbracket N_{1}\right]^{\vec{x}}, \# \llbracket N_{2} \rrbracket^{\vec{x}}\right]$. By applying Lemma 4.2(v), we obtain $\vdash \mathrm{Ifz}_{n}:(\vec{\beta} \rightarrow$ int $) \rightarrow(\vec{\beta} \rightarrow \alpha) \rightarrow(\vec{\beta} \rightarrow \alpha) \rightarrow \vec{\beta} \rightarrow \alpha$. By the hypothesis IH1, we get $\vdash \llbracket L \rrbracket^{\vec{x}}: \vec{\beta} \rightarrow$ int and $\vdash \llbracket N_{i} \rrbracket^{\vec{x}}: \vec{\beta} \rightarrow \alpha$ for $i \in\{1,2\}$, and thus by Proposition 3.5(i), we conclude $\vdash \mathrm{If} z_{n} @\left[\# \llbracket L \rrbracket^{\vec{x}}, \# \llbracket N_{1} \rrbracket^{\vec{x}}, \# \llbracket N_{2} \rrbracket^{\vec{x}}\right]: \vec{\beta} \rightarrow \alpha$.

Case $\left(\rightarrow_{\mathrm{I}}\right)$ : Assume that $\Gamma \vdash \lambda z \cdot M^{\prime}\langle\sigma\rangle: \alpha_{1} \rightarrow \alpha_{2}$, for $\alpha=\alpha_{1} \rightarrow \alpha_{2}$, because there is $\Delta=$ $y_{1}: \delta_{1}, \ldots, y_{m}: \delta_{m}$ such that $\sigma \models \Delta$ and $\Gamma, \Delta, z: \alpha_{1} \vdash M^{\prime}: \alpha_{2}$. Then $\sigma \vDash \Delta$ entails $\sigma=\left[y_{1} \leftarrow\left(\rho_{1}, N_{1}\right), \ldots, y_{m} \leftarrow\left(\rho_{m}, N_{m}\right)\right]$ for appropriate $\vec{\rho}, \vec{N}$. By definition, we have $\llbracket \lambda z \cdot M^{\prime}\langle\sigma\rangle \rrbracket^{x_{1}, \ldots, x_{n}}=\left(\sigma \sigma, M^{\prime}\right)^{\vec{x}, z}=\llbracket M^{\prime} \rrbracket^{y_{1}, \ldots, y_{m}, \vec{x}, z} @\left[\#\left(\rho_{1}, N_{1}\right), \ldots, \#\left(\rho_{m}, N_{m}\right)\right]$. By applying IH1, we obtain $\vdash \llbracket M^{\prime} \rrbracket^{\vec{y}, \vec{x}, z}: \vec{\delta} \rightarrow \vec{\beta} \rightarrow \alpha_{1} \rightarrow \alpha_{2}$. From IH2, we get $\vdash\left(\sigma_{1}, N_{1}\right): \delta_{1} \cdots \vdash\left(\sigma_{m}, N_{m}\right): \delta_{m}$. Finally, by Proposition 3.5(i), we derive $\vdash \llbracket M^{\prime} \rrbracket^{\vec{y}, \vec{x}, z} @\left[\#\left(\sigma_{1}, N_{1}\right), \ldots, \#\left(\sigma_{m}, N_{m}\right)\right]: \vec{\beta} \rightarrow \alpha_{1} \rightarrow \alpha_{2}$.
Case $\left(\rightarrow_{\mathrm{E}}\right)$ : In this case $\Gamma \vdash M_{1} \cdot M_{2}: \alpha$ since, for some $\delta \in \mathbb{T}, \Gamma \vdash M_{1}: \delta \rightarrow \alpha$ and $\Gamma \vdash M_{2}: \delta$. By definition, $\llbracket M_{1} \cdot M_{2} \rrbracket^{\vec{x}}=$ Apply $_{n} @\left[\# \llbracket M_{1} \rrbracket^{\vec{x}}, \# \llbracket M_{2} \rrbracket^{\vec{x}}\right]$. By Lemma 4.2(ii), we get $\vdash$ Apply $_{n}:(\vec{\beta} \rightarrow \delta \rightarrow$ $\alpha) \rightarrow(\vec{\beta} \rightarrow \delta) \rightarrow \vec{\beta} \rightarrow \alpha$. By IH1, we obtain $\vdash \llbracket M_{1} \rrbracket^{\vec{x}}: \vec{\beta} \rightarrow \delta \rightarrow \alpha$ and $\vdash \llbracket M_{2} \rrbracket^{\vec{x}}: \vec{\beta} \rightarrow \delta$. Conclude,
by Proposition 3.5(i), that $\vdash$ Apply $_{n} @\left[\# \llbracket M_{1} \rrbracket^{\vec{x}}, \# \llbracket M_{2} \rrbracket \overrightarrow{\vec{x}}\right]: \vec{\beta} \rightarrow \alpha$.
We now consider the cases concerning (ii).
Case $\left(\sigma_{0}\right)$ : In this case []$\models \emptyset$, so we have nothing to prove.
Case $(\sigma)$ : In this case $\Gamma=\Gamma^{\prime}, x_{n}: \beta_{n}$ and $\sigma=\sigma^{\prime}+\left[x_{n} \leftarrow(\rho, N)\right] \models \Gamma^{\prime}, x_{n}: \beta_{n}$, because $\sigma^{\prime} \models \Gamma^{\prime}, \rho \models \Delta$ and $\Delta \vdash N: \beta_{n}$, for some $\Delta=y_{1}: \delta_{1}, \ldots, y_{m}: \delta_{m}$. By IH2 on $\sigma^{\prime} \models \Gamma^{\prime}$, we get $\left(\sigma\left(x_{i}\right)\right)=\left(\sigma^{\prime}\left(x_{i}\right)\right): \beta_{i}$, for all $i \in\{1, \ldots, n-1\}$. We show $((\rho, N)): \beta_{n}$. By IH1, we get $\vdash \llbracket N \rrbracket^{y_{1}, \ldots, y_{m}}: \delta_{1} \rightarrow \cdots \rightarrow$ $\delta_{m} \rightarrow \beta_{n}$. By applying IH2 on $\rho \models \Delta$, we get $\left(\rho\left(y_{j}\right)\right): \delta_{j}$, for all $j \in\{1, \ldots, m\}$. Since $(\rho, N)=$ $\llbracket N \rrbracket^{\vec{y}} @\left[\#\left(\rho\left(y_{1}\right)\right), \ldots, \#\left(\rho\left(y_{m}\right)\right)\right]$, we conclude $\vdash(\rho, N): \beta_{n}$, by Proposition 3.5(i).

Proof. [Proof of Theorem 4.7] We prove $\sigma \triangleright M \Downarrow_{d} V \Rightarrow\left(\sigma, M D \leftrightarrow_{c} \llbracket V \rrbracket\right.$ by induction on a derivation of $\sigma \triangleright M \Downarrow_{d} V$. We let $\operatorname{dom}(\sigma)=\left\{x_{1}, \ldots, x_{n}\right\}$ and sometimes use the convenient notation $\left.\# \mid \sigma(\vec{x})\right)=$ $\#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)$.
Case (nat): Then $M=V=\underline{k}$, for some $k \geq 0$. Recall that we assume $k=\# \mathrm{k}$. Then using Lemma 4.1(i), $(\sigma, \underline{k})=\llbracket \underline{k} \rrbracket^{x_{1}, \ldots, x_{n}} @[\#(\sigma(\vec{x}))]=\operatorname{Pr}_{1}^{n+1} @[k, \#(\sigma(\vec{x}))] \rightarrow{ }_{\mathrm{c}} \#^{-1}(k)_{\mathrm{c}}$ $-\operatorname{Pr}_{1}^{1} @[k]=\llbracket \underline{k} \rrbracket$
Case 2: (fun) We have $M=\lambda z \cdot M^{\prime}\langle\rho\rangle$ and $V=\lambda x \cdot M^{\prime}\langle\sigma+\rho\rangle$, with $\operatorname{dom}(\sigma) \cap \operatorname{dom}(\rho)=\emptyset$. Say, $\operatorname{dom}(\rho)=\left\{y_{1}, \ldots, y_{m}\right\}$. Then

$$
\begin{aligned}
\left(\sigma, \lambda z \cdot M^{\prime}\langle\rho\rangle\right) & =\llbracket \lambda z \cdot M^{\prime}\langle\rho\rangle \rrbracket^{x_{1}, \ldots, x_{n}} @\left[\#(\sigma(\vec{x}) D]=\left(\rho, M^{\prime}\right)^{\vec{x}, z} @[\#(\sigma(\vec{x}) D]\right. \\
& =\llbracket M^{\prime} \rrbracket^{\vec{y}, \vec{x}, z} @[\#(\rho(\vec{y})), \#(\sigma(\vec{x}))]=\left(\sigma+\rho, M^{\prime}\right)^{z}=\llbracket \lambda z \cdot M^{\prime}\langle\sigma+\rho\rangle \rrbracket
\end{aligned}
$$

The case follows by reflexivity of $\leftrightarrow_{c}$.
Case (var): We have $M=x_{i}, \sigma\left(x_{i}\right)=(\rho, N)$ and $\rho \triangleright N \Downarrow_{d} V$. Then, using Lemma 4.1(i), we have $\left(\sigma, x_{i}\right)=\llbracket x_{i} \rrbracket^{x_{1}, \ldots, x_{n}} @[\#(\sigma(\vec{x}))]=\operatorname{Pr}_{i}^{n} @[\#(\sigma(\vec{x}))] \rightarrow_{\mathrm{c}}\left(\sigma\left(x_{i}\right)\right)=(\rho, N)$ We conclude since, by IH, we have $(\rho, N\rceil \leftrightarrow_{c} \llbracket V \rrbracket$.

Case $\left(\beta_{v}\right): M=M_{1} \cdot M_{2}, \sigma \triangleright M_{1} \Downarrow_{d} \lambda z . M_{1}^{\prime}\langle\rho\rangle$ and $\rho+\left[z \leftarrow\left(\sigma, M_{2}\right)\right] \triangleright M_{1}^{\prime} \Downarrow_{d} V$. Easy calculations give:

$$
\begin{aligned}
& \left(\sigma, M_{1} \cdot M_{2}\right) \\
& =\llbracket M_{1} \cdot M_{2} \rrbracket^{x_{1}, \ldots, x_{n}} @\left[\#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& =\text { Apply }_{n} @\left[\llbracket M_{1} \rrbracket^{\vec{x}}, \# \llbracket M_{2} \rrbracket^{\vec{x}}, \#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& =\left(\sigma, M_{1}\right) @\left[\#\left(\sigma, M_{2}\right)\right]
\end{aligned}
$$

By IH on $\sigma \triangleright M_{1} \Downarrow_{d} \lambda z \cdot M_{1}^{\prime}\langle\rho\rangle$, we have $\left(\sigma, M_{1}\right) \leftrightarrow_{c} \llbracket \lambda z \cdot M_{1}^{\prime}\langle\rho\rangle \rrbracket=\left(\rho, M_{1}^{\prime}\right)^{z}$. Calling $\operatorname{dom}(\rho)=$ $\left\{y_{1}, \ldots, y_{m}\right\}$, we get

$$
\begin{array}{rlrl}
\left(\sigma, M_{1}\right) @\left[\#\left(\sigma, M_{2}\right)\right] & \leftrightarrow_{c}\left(\rho, M_{1}^{\prime}\right)^{z} @\left[\#\left(\sigma, M_{2}\right)\right], & \text { by def. of } \leftrightarrow_{c} \text { and Lemma 2.11, } \\
& =\llbracket M_{1}^{\prime} \rrbracket^{y_{1}, \ldots, y_{m}, z} @\left[\#(\rho(\vec{y})), \#\left(\sigma, M_{2}\right)\right] & \\
& =\left(\rho+\left[z \leftarrow\left(\sigma, M_{2}\right)\right], M_{1}^{\prime}\right)
\end{array}
$$

By IH conclude $\left(\rho+\left[z \leftarrow\left(\sigma, M_{2}\right)\right], M_{1}^{\prime}\right) \leftrightarrow_{c} \llbracket V \rrbracket$.
Case $(\operatorname{pr}): M=\operatorname{pred} M^{\prime}, V=\underline{n}$ and $\sigma \triangleright M^{\prime} \Downarrow_{d} \underline{n+1}$, for some $n \geq 0$. By IH we get $\left(\sigma, M^{\prime}\right) \leftrightarrow_{c} \llbracket n+1 \rrbracket=$
$\#^{-1}(n+1)$ and, since the $(n+1)$-th numeral machine is in final state, we derive $\left(\sigma, M^{\prime}\right) \rightarrow{ }_{c} \#^{-1}(n+1)$.

Conclude as follows:

$$
\begin{aligned}
& \left(\sigma, \text { pred } M^{\prime}\right)=\llbracket \operatorname{pred} M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}} @\left[\#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& =\operatorname{Pred}_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}, \#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& \rightarrow_{\mathrm{c}}\left\langle R_{0}=\#\left(\llbracket M^{\prime} \rrbracket^{\vec{x}} @[\#(\sigma(\vec{x}))]\right), \vec{R}, 0 \leftarrow \operatorname{Pred}(0) ; \text { Call } 0,[]\right\rangle \text {, by Lemma 4.1(iii), } \\
& =\left\langle R_{0}=\#\left(\sigma, M^{\prime}\right), \vec{R}, ; 0 \leftarrow \operatorname{Pred}(0) ; \text { Call } 0,[]\right\rangle \\
& \rightarrow{ }_{c}\left\langle R_{0}=n+1, \vec{R}, 0 \leftarrow \operatorname{Pred}(0) ; \text { Call } 0,[]\right\rangle \rightarrow{ }_{c} \#^{-1}(n)
\end{aligned}
$$

Case $\left(\mathrm{pr}_{0}\right)$ : Analogous to the previous case, using the fact that $\operatorname{Pred}(0)$ is 0.
Case 7: (sc) $M=\operatorname{succ} M^{\prime}, V=\underline{n+1}$ and $\sigma \triangleright M^{\prime} \Downarrow_{d} \underline{n}$, for some $n \geq 0$. By IH we get $\left(\sigma, M^{\prime}\right) \leftrightarrow_{c} \llbracket \underline{n} \rrbracket=$ $\#^{-1}(n)$ and, since the $n$-th numeral machine is in final state, we derive $\left(\sigma, M^{\prime}\right) \rightarrow_{c} \#^{-1}(n)$. Conclude as follows:

$$
\begin{aligned}
\left(\sigma, \operatorname{succ} M^{\prime}\right) & =\llbracket \operatorname{succ} M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}} @\left[\# \backslash \sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right) D\right] \\
& \left.=\operatorname{Succ}_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}, \# \ \sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& \left.\rightarrow{ }_{c}\left\langle R_{0}=\#\left(\llbracket M^{\prime} \rrbracket^{\prime} @[\# \ \sigma(\vec{x}) D]\right), \vec{R}, 0 \leftarrow \operatorname{Succ}(0) ; \operatorname{Call} 0,[]\right\rangle, \text { by Lemma 4.1(iii) }\right) \\
& \left.=\left\langle R_{0}=\# \backslash \sigma, M^{\prime}\right), \vec{R}, ; 0 \leftarrow \operatorname{Succ}(0) ; \operatorname{Call} 0,[]\right\rangle \\
& \rightarrow{ }_{c}\left\langle R_{0}=n, \vec{R}, 0 \leftarrow \operatorname{Succ}(0) ; \operatorname{Call} 0,[]\right\rangle \rightarrow{ }_{c} \quad \#^{-1}(n+1)
\end{aligned}
$$

Case 8: $\left(\right.$ ifz $\left._{>0}\right) \quad M=\operatorname{ifz}\left(L, N_{1}, N_{2}\right), \sigma \triangleright L \Downarrow_{d} \underline{n+1}, \sigma \triangleright N_{2} \Downarrow_{d} V$ for some $n \geq 0$. By IH we get $(\sigma, L) \leftrightarrow_{c}$ $\llbracket n+1 \rrbracket$, and since the $(n+1)$-th numeral machine is in final state, we derive $\left(\sigma, L \downarrow \rightarrow{ }_{\mathrm{c}} \#^{-1}(n+1)\right.$. Then

$$
\begin{aligned}
& \left(\sigma, \mathbf{i f z}\left(L, N_{1}, N_{2}\right)\right)=\llbracket \mathbf{i f z}\left(L, N_{1}, N_{2}\right) \rrbracket^{x_{1}, \ldots, x_{n}} @\left[\#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& =\mathrm{If} \mathrm{z}_{n} @\left[\# \llbracket L \rrbracket^{x_{1}, \ldots, x_{n}}, \# \llbracket N_{1} \rrbracket^{x_{1}, \ldots, x_{n}}, \# \llbracket N_{2} \rrbracket^{x_{1}, \ldots, x_{n}}, \#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& \rightarrow{ }_{\mathrm{c}}\left\langle R_{0}=\#(\sigma, L), R_{1}=\#\left(\sigma, N_{1}\right), R_{2}=\#\left(\sigma, N_{2}\right), \vec{R}, 0 \leftarrow \text { Test }(0,1,2) ; \text { Call } 0,[]\right\rangle, \\
& \text { by Lemma 4.1(v), } \\
& \rightarrow \mathrm{c}\left\langle R_{0}=n+1, R_{1}=\#\left(\sigma, N_{1}\right), R_{2}=\#\left(\sigma, N_{2}\right), \vec{R}, 0 \leftarrow \operatorname{Test}(0,1,2) ; \text { Call } 0,[]\right\rangle \\
& \rightarrow c\left(\sigma, N_{2}\right)
\end{aligned}
$$

We conclude since, by IH, $\left(\sigma, N_{2}\right) \leftrightarrow_{c} \llbracket V \rrbracket$.
Case 9: $\left(\mathrm{ifz}_{0}\right) \quad M=\operatorname{ifz}\left(L, N_{1}, N_{2}\right), \sigma \triangleright L \Downarrow_{d} \underline{0}, \sigma \triangleright N_{1} \Downarrow_{d} V$. By IH we get $\left(\sigma, L D \leftrightarrow_{c} \llbracket \underline{0} \rrbracket\right.$, and since the $(n+1)$-th numeral machine is in final state, we derive $(\sigma, L) \rightarrow{ }_{\mathrm{c}} \#^{-1}(0)$. Then

$$
\begin{aligned}
& \left(\sigma, \mathbf{i f z}\left(L, N_{1}, N_{2}\right)\right)=\llbracket \mathbf{i f z}\left(L, N_{1}, N_{2}\right) \rrbracket^{x_{1}, \ldots, x_{n}} @\left[\#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& =\mathrm{If} \mathrm{z}_{n} @\left[\# \llbracket L \rrbracket^{x_{1}, \ldots, x_{n}}, \# \llbracket N_{1} \rrbracket^{x_{1}, \ldots, x_{n}}, \# \llbracket N_{2} \rrbracket^{x_{1}, \ldots, x_{n}}, \#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& \rightarrow{ }_{c}\left\langle R_{0}=\#(\sigma, L), R_{1}=\#\left(\sigma, N_{1}\right), R_{2}=\#\left(\sigma, N_{2}\right), \vec{R}, 0 \leftarrow \operatorname{Test}(0,1,2) ; \text { Call } 0,[]\right\rangle, \\
& \text { by Lemma 4.1(v), } \\
& \rightarrow \mathrm{c}\left\langle R_{0}=0, R_{1}=\#\left(\sigma, N_{1}\right), R_{2}=\#\left(\sigma, N_{2}\right), \vec{R}, 0 \leftarrow \operatorname{Test}(0,1,2) ; \text { Call } 0,[]\right\rangle \\
& \rightarrow \mathrm{c}\left(\sigma, N_{1}\right)
\end{aligned}
$$

We conclude since, by IH, $\left(\sigma, N_{1}\right) \leftrightarrow_{c} \llbracket V \rrbracket$.

Case (fix): Then $M=\operatorname{fix} M^{\prime}$ and $\sigma \triangleright M^{\prime} \cdot\left(\mathrm{fix} M^{\prime}\right)$. Then

$$
\begin{aligned}
& \left(\sigma, \text { fix } M^{\prime}\right)=\llbracket \mathrm{fix} M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}} @\left[\#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& =\mathrm{Y}_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{x_{1}, \ldots, x_{n}}, \#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& \rightarrow{ }_{\mathrm{c}} \llbracket M^{\prime} \rrbracket^{\vec{x}} @\left[\#(\sigma(\vec{x})), \#\left(\mathrm{Y}_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{\vec{x}}, \#(\sigma(\vec{x}))\right]\right)\right] \\
& =\llbracket M^{\prime} \rrbracket^{\vec{x}} @\left[\#(\sigma(\vec{x})), \#\left(\llbracket \mathrm{fix} M^{\prime} \rrbracket^{\vec{x}} @[\#(\sigma(\vec{x}))]\right)\right], \quad \text { by Lemma 4.1(ii), } \\
& \mathrm{c} \leftarrow \text { Apply }{ }_{n} @\left[\# \llbracket M^{\prime} \rrbracket^{\vec{x}}, \# \llbracket \mathrm{fix} M^{\prime} \rrbracket^{\vec{x}}, \#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& =\llbracket M^{\prime} \cdot\left(\mathbf{f i x} M^{\prime}\right) \rrbracket^{x_{1}, \ldots, x_{n}} @\left[\#\left(\sigma\left(x_{1}\right)\right), \ldots, \#\left(\sigma\left(x_{n}\right)\right)\right] \\
& =\left(\sigma, M^{\prime} \cdot\left(\operatorname{fix} M^{\prime}\right)\right. \text {. }
\end{aligned}
$$

This concludes the proof.
Proof. [Proof of Theorem 4.13(i)] For an EPCF term $M$, an EPCF value $V$ and an explicit substitution $\sigma$, we show $\sigma \triangleright M \Downarrow_{d} V \Rightarrow(\sigma, M)^{*} \Downarrow([], V)^{*}$ by induction on a derivation of $\sigma \triangleright M \Downarrow_{d} V$.

Case (nat): In this case $M=V=\underline{n}$ for some $n \geq 0$. By definition, $(\sigma, \underline{n})^{*}=\underline{n}$, so we apply PCF's rule (val) and get $\underline{n} \Downarrow \underline{n}$.

Case (fun): We have $M=\lambda x \cdot M^{\prime}\left\langle\sigma^{\prime}\right\rangle$ and $V=\lambda x \cdot M^{\prime}\left\langle\sigma+\sigma^{\prime}\right\rangle$.
As $\left(\sigma, \lambda x \cdot M^{\prime}\left\langle\sigma^{\prime}\right\rangle\right)^{*}=\left([], \lambda x \cdot M^{\prime}\left\langle\sigma+\sigma^{\prime}\right\rangle\right)^{*}=\lambda x \cdot\left(\sigma+\sigma^{\prime}, M^{\prime}\right)^{*}$ and the latter is a PCF value, we can apply PCF's rule (val) to conclude $\left(\sigma, \lambda x \cdot M^{\prime}\left\langle\sigma^{\prime}\right\rangle\right)^{*} \Downarrow\left([], \lambda x \cdot M^{\prime}\left\langle\sigma+\sigma^{\prime}\right\rangle\right)^{*}$.
Case (var): In this case $M=x, \sigma(x)=(\rho, N)$ and $\rho \triangleright N \Downarrow_{d} V$. By IH $(\rho, N)^{*} \Downarrow([], V)^{*}$. We conclude since $(\sigma, M)^{*}=(\rho, N)^{*}$.

Case $\left(\beta_{v}\right)$ : In this case $M=M_{1} \cdot M_{2}$ with $\sigma \triangleright M_{1} \Downarrow_{d} \lambda x . M_{1}^{\prime}\langle\rho\rangle$, wlog $x \notin \operatorname{dom}(\rho+\sigma)$, and $\rho+[x \leftarrow$ $\left.\left(\sigma, M_{2}\right)\right] \triangleright M_{1}^{\prime} \Downarrow_{d} V$. By IH we obtain $\left(\sigma, M_{1}\right)^{*} \Downarrow\left([], \lambda x . M_{1}^{\prime}\langle\rho\rangle\right)^{*}$ and $\left(\rho+\left[x \leftarrow\left(\sigma, M_{2}\right)\right], M_{1}^{\prime}\right)^{*} \Downarrow([], V)^{*}$. By Lemma 4.12(i) $\left(\rho+\left[x \leftarrow\left(\sigma, M_{2}\right)\right], M_{1}^{\prime}\right)^{*}=\left(\rho, M_{1}^{\prime}\right)^{*}\left[\left(\sigma, M_{2}\right)^{*} / x\right]$. By definition, $\left([], \lambda x \cdot M_{1}^{\prime}\langle\rho\rangle\right)^{*}=$ $\lambda x \cdot\left(\rho, M_{1}^{\prime}\right)^{*}$ and $\left(\sigma, M_{1}\right)^{*} \cdot\left(\sigma, M_{2}\right)^{*}=\left(\sigma, M_{1} \cdot M_{2}\right)^{*}$. Thus

$$
\frac{\left(\sigma, M_{1}\right)^{*} \Downarrow \lambda x \cdot\left(\sigma^{\prime}, M_{1}^{\prime}\right)^{*} \quad\left(\sigma^{\prime}, M_{1}^{\prime}\right)^{*}\left[\left(\sigma, M_{2}\right)^{*} / x\right] \Downarrow([], V)^{*}}{\left(\sigma, M_{1} \cdot M_{2}\right)^{*} \Downarrow([], V)^{*}}\left(\beta_{v}\right)
$$

Case (fix): In this case $M=\operatorname{fix} N$ and $\sigma \triangleright N \cdot(\operatorname{fix} N) \Downarrow_{d} V$. From the IH we get $(\sigma, N \cdot(\mathbf{f i x} N))^{*} \Downarrow([], V)^{*}$. By definition, we have $(\sigma, N \cdot(\operatorname{fix} N))^{*}=(\sigma, N)^{*} \cdot\left(\operatorname{fix}(\sigma, N)^{*}\right)$ and $\operatorname{fix}(\sigma, N)^{*}=(\sigma, \mathrm{fix} N)^{*}$. By applying PCF's rule (fix), we obtain

$$
\frac{(\sigma, N \cdot(\operatorname{fix} N))^{*} \Downarrow([], V)^{*}}{(\sigma, \operatorname{fix} N)^{*} \Downarrow([], V)^{*}}(\mathrm{fix})
$$

All other cases derive straightforwardly from the IH.
Proof. [Proof of Theorem 4.13(ii)] For a PCF program $P$ and PCF value $U$, we show that $P \Downarrow U$ entails:

$$
\forall(\sigma, M) \in P^{\dagger}, \exists V \in \operatorname{Val} .\left(\sigma \triangleright M \Downarrow_{d} V \text { and }([], V) \in U^{\dagger}\right)
$$

By induction on the lexicographically ordered pairs, whose first component is the length of a derivation of $P \Downarrow U$ and second component is $|(\sigma, M)|$.

First, consider the case $M=y$ and $\sigma(y)=(\rho, N)$, with $(\rho, N) \in P^{\dagger}$. In this case, the length of the derivation $(\rho, N)^{*} \Downarrow U$ remained unchanged, while $|(\rho, N)|<|(\sigma, M)|$. Thus, we may use the IH and conclude by applying (var). Therefore, in the following we assume that $M$ is not a variable.

Case (val): In this case $P=U$. Given $(\sigma, M) \in P^{\dagger}$, we distinguish several cases:

- Case $P=U=\lambda x . P_{0}$. Then, $M=\lambda x \cdot M_{0}\langle\rho\rangle$ with $P_{0}=\left(\sigma+\rho, M_{0}\right)^{*}$. Setting $V=\lambda x . M_{0}\langle\sigma+\rho\rangle$ we obtain $M \Downarrow_{d} V$ by (fun) with ( $[, V)^{*}=\lambda x .\left(\sigma+\rho, M_{0}\right)=\lambda x \cdot P_{0}=U$.
- $P=U=\mathbf{0}$. It follows $M=V=\mathbf{0}$ and $\sigma \triangleright \mathbf{0} \Downarrow_{d} \mathbf{0}$ by (nat).
- $P=U=\operatorname{succ}(\underline{n})$, for some $n \in \mathbb{N}$, and $M$ is not a variable.

There are two possibilities:

- $M=\operatorname{succ}(\underline{n})$ in which case we are done, since $\sigma \triangleright \underline{n+1} \Downarrow_{d} \underline{n+1}$.
- $M=\operatorname{succ}(\underline{y})$ with $\sigma(y)=(\rho, N)$ and $(\rho, N) \in \underline{n}^{\dagger}$. Again, the length of the derivation $(\rho, N)^{*} \Downarrow \underline{n}$ is unchanged, while $|(\rho, N)|<|(\sigma, M)|$. Once applied the IH, we conclude by (var) + (sc).

Case $\left(\beta_{v}\right): P=P_{1} \cdot P_{2}$ with $P_{1} \Downarrow \lambda x \cdot Q_{1}$ and $Q_{1}\left[P_{2} / x\right] \Downarrow U$ for some $Q_{1}$. Notice that, since $P$ is closed so are $P_{1}, P_{2}$ and hence $\mathrm{FV}\left(Q_{1}\right) \subseteq\{x\}$. Now, $(\sigma, M)^{*}=P$ entails $M=M_{1} \cdot M_{2}$ with $\left(\sigma, M_{1}\right) \in P_{1}^{\dagger}$ and $\left(\sigma, M_{2}\right) \in P_{2}^{\dagger}$. By ind. hyp., there is $V^{\prime} \in \mathrm{Val}$ such that $\sigma \triangleright M_{1} \Downarrow_{d} V_{1}$ with $\left([], V_{1}\right) \in\left(\lambda x . Q_{1}\right)^{\dagger}$. This implies $V_{1}=\lambda x . N_{1}\langle\rho\rangle$ for some $\left(\rho, N_{1}\right) \in Q_{1}^{\dagger}$. By Lemma 4.12(ii), we get $\left(\rho+\left[x \leftarrow\left(\sigma, M_{2}\right)\right], N_{1}\right) \in$ $\left(Q_{1}\left[P_{2} / x\right]\right)^{\dagger}$. By ind. hyp., there is $V \in \operatorname{Val}$ such that $\rho+\left[x \leftarrow\left(\sigma, M_{2}\right)\right] \triangleright N_{1} \Downarrow_{d} V$ and $V \in U^{\dagger}$. Conclude by EPCF's $\left(\beta_{v}\right)$.

Case (fix): $P=\operatorname{fix} Q$ and $Q \cdot(\operatorname{fix} Q) \Downarrow V$. Then $(\sigma, M) \in P^{\dagger}$ entails $M=\operatorname{fix} N$ with $(\sigma, N) \in Q^{\dagger}$. It follows that $(\sigma, N \cdot(\operatorname{fix} N)) \in(Q \cdot(\mathbf{f i x} Q))^{\dagger}$, therefore by IH we get $\sigma \triangleright N \cdot(\operatorname{fix} N) \Downarrow_{d} V$ for some $V \in U^{\dagger}$. We conclude by applying EPCF's rule (fix).
All other cases derive straightforwardly from the IH.


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[^1]:    ${ }^{6}$ The reader interested in a comparison with other abstract machines or formalisms is invited to consult [14].

[^2]:    ${ }^{7}$ In other words, we set $\left.\llbracket M \rrbracket^{\vec{x}}=\ \llbracket\right], M \emptyset^{\vec{x}}$.

